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Carlos III de Madrid  
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# Session 2

## Electronic circuits analysis

Electronic Components and Circuits

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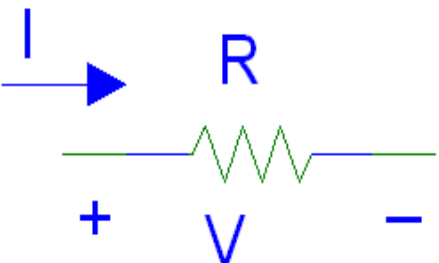
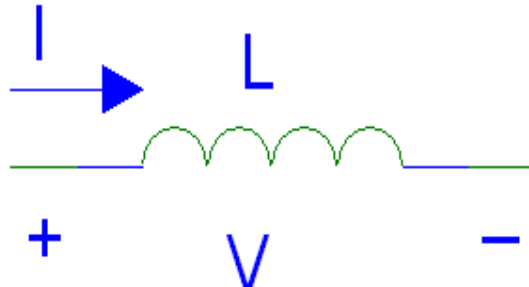
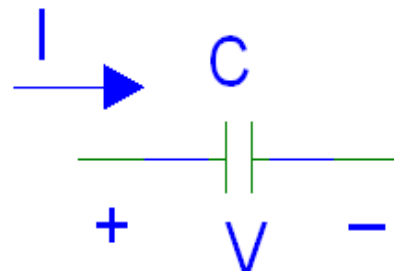
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# Electronic circuits analysis

## OBJECTIVES

- R, L, C circuits
- Application of circuit analysis theorems
- Signal generators and dependent sources
- Transient response: Time constants
- Permanent sinusoidal regime (PSR):  
Frequency response

# R L C circuits

			
Eq.	$V = I \cdot R$	$V = L \cdot \frac{dI}{dt}$	$I = C \cdot \frac{dV}{dt}$
DC	$R = 1k\Omega$ $V = 5V$ $I = 5mA$	$I_{DC} = const$ $s.c. \rightarrow V = 0$	$V_{DC} = const$ $o.c. \rightarrow I = 0$
AC	$v = 5 \sin(\omega t)$ $V = 5V_{peak}$ $I = 5mA_{peak}$	$i = I_0 \sin(\omega t)$ $v = L\omega I_0 \cos(\omega t)$ $Z_L = j\omega L$	$v = V_0 \sin(\omega t)$ $i = C\omega V_0 \cos(\omega t)$ $Z_C = 1 / j\omega C$

# Circuit analysis in DC and AC

- Ohm's law and the concept of impedance
- Kirchoff's circuit laws for voltages and currents
- Superposition Theorem
- Thevenin and Norton theorems
- Mobility of Voltage and Current sources

# Ohm's law and the concept of impedance

$$V = I \cdot R$$

$$V_{DC} = R \cdot I_{DC}$$

$$v(t) = R \cdot i(t)$$

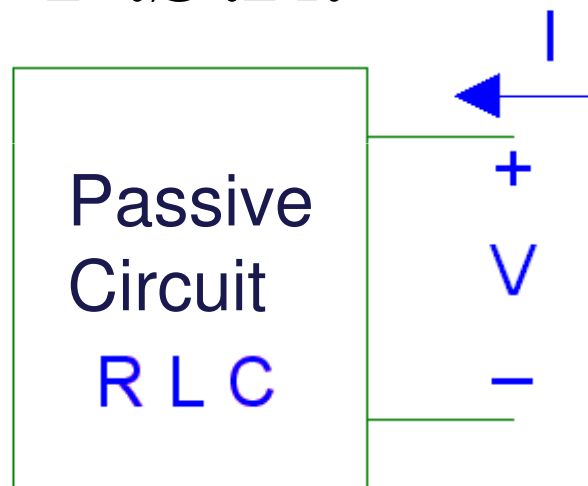
$$V_{AC} = R \cdot I_{AC}$$

$$V_p = R \cdot I_p \quad \phi_R = 0$$

$$V_{RMS} = R \cdot I_{RMS}$$

*P.S.R.*

$$V = I \cdot Z$$



$$Z = \frac{V}{I}$$

$$Y = \frac{1}{Z}$$

# Ohm's law and the concept of impedance

$$\begin{array}{l} i = I_0 \cos(\omega t + \phi_I) \\ v = V_0 \cos(\omega t + \phi_V) \end{array} \quad \longrightarrow \quad \begin{array}{l} I = |I_0|_{\phi_I} \\ V = |V_0|_{\phi_V} \end{array}$$

$$|V| = |I| \cdot |Z| \quad \phi_V = \phi_I + \phi_Z$$

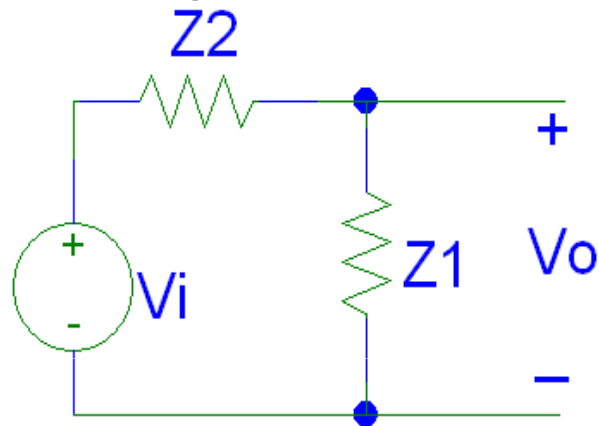
$$Z_R = R \quad Z_L = j\omega L \quad Z_C = \frac{1}{j\omega C}$$

# Kirchoff laws for voltages and currents

$$\sum V's \Big|_{LOOP} = 0$$

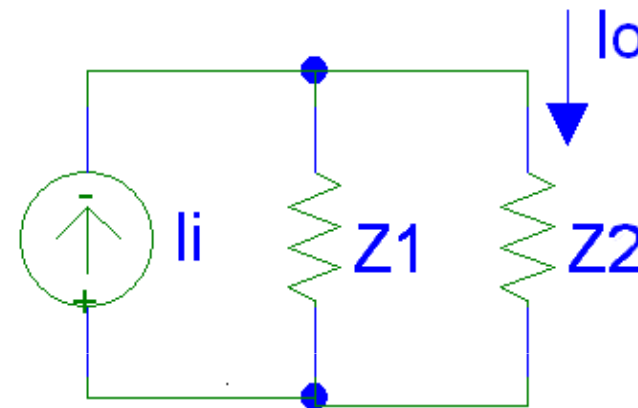
$$\sum I's \Big|_{NODE} = 0$$

Voltage Divider



$$V_o = V_i \frac{Z_1}{Z_1 + Z_2}$$

Current Divider

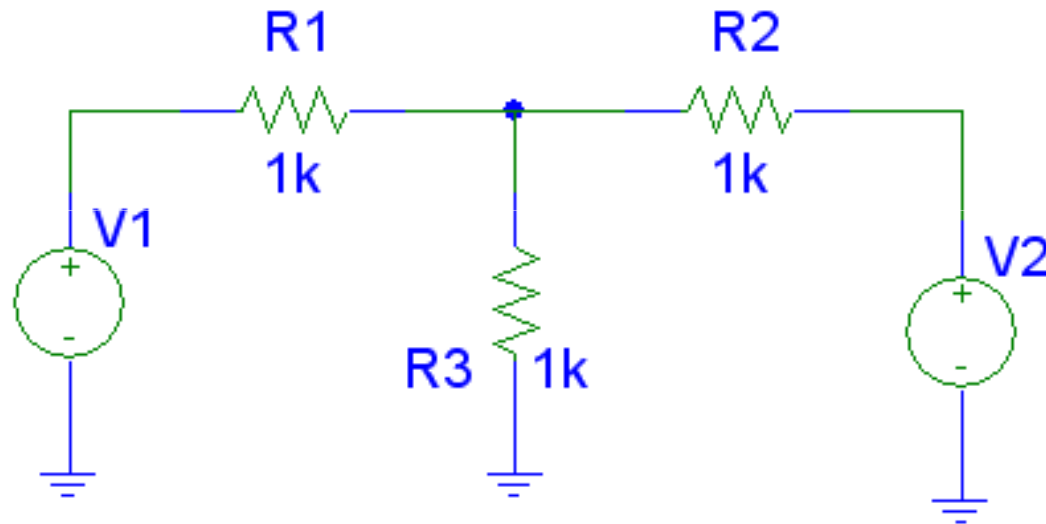


$$I_o = I_i \frac{Y_2}{Y_1 + Y_2} = I_i \frac{Z_1}{Z_1 + Z_2}$$

# Superposition theorem

- Only for linear circuits

A circuit with multiple independent sources can be analyzed separately for each of the generators (assuming canceled the rest) and adding the individual responses to the final.





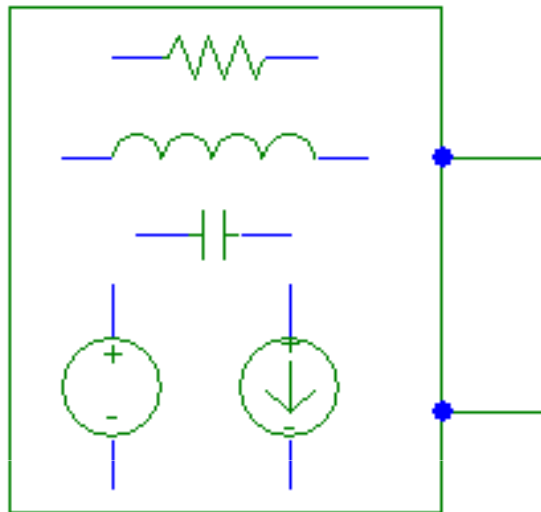
# Theorems of Thevenin and Norton

- Any linear circuit can be replaced by an equivalent voltage source and a series impedance (between the two terminals of the circuit under consideration).
- Any linear circuit can be replaced by an equivalent current generator and a parallel impedance (between the two terminals ).

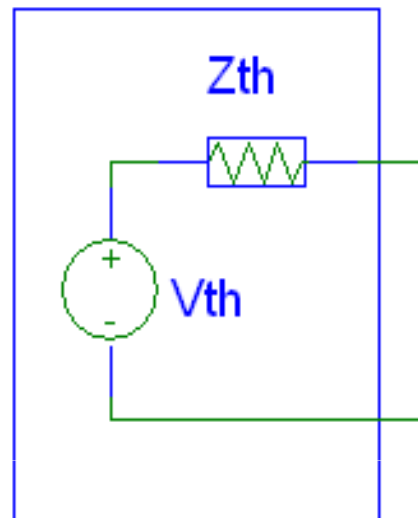
How do I get? Review

# Theorems of Thevenin and Norton

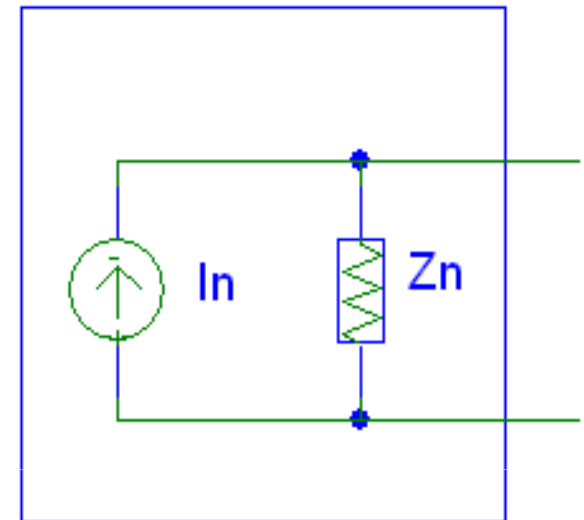
Linear Circuit



Thevenin equivalent



Norton equivalent



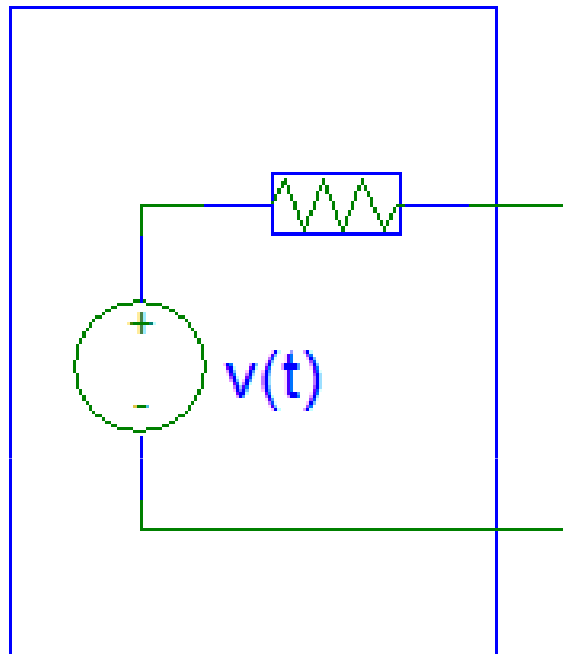
- Apply Thevenin's theorem to relate  $V_{th}$ ,  $Z_{th}$  with  $I_n$ ,  $Z_n$
- Apply Norton's theorem to relate  $I_n$ ,  $Z_n$  with  $V_{th}$ ,  $Z_{th}$

# Types of signal generators

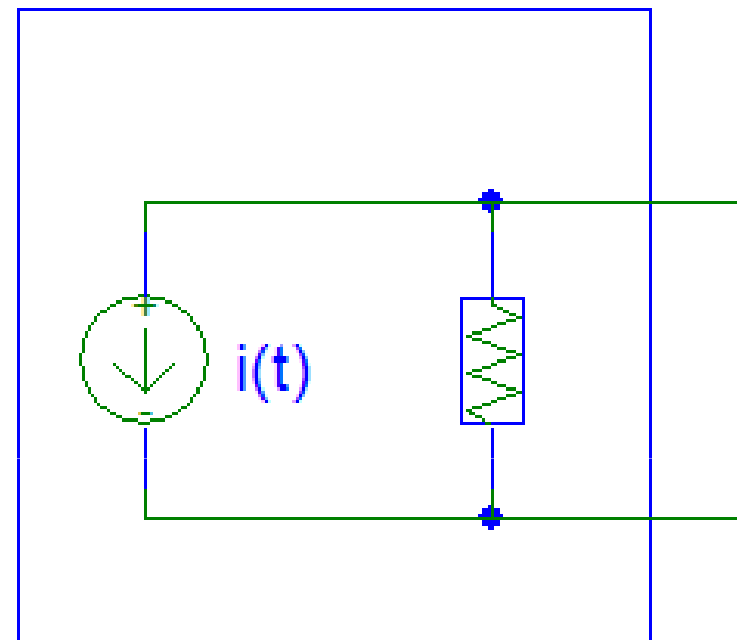
- Voltage and current generators
- Dependent sources
- Real generators and ideal generators

# Independent generators

## Equivalent voltage generator

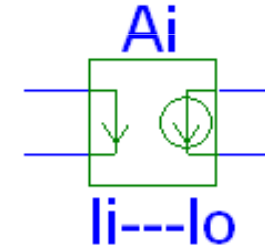
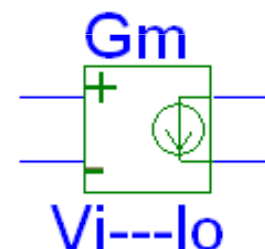
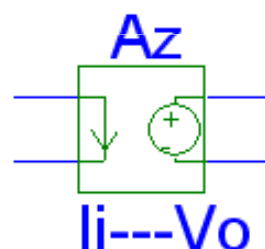
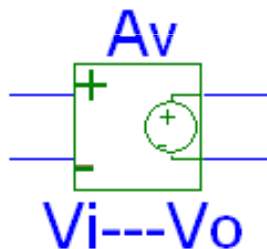


## Equivalent current generator



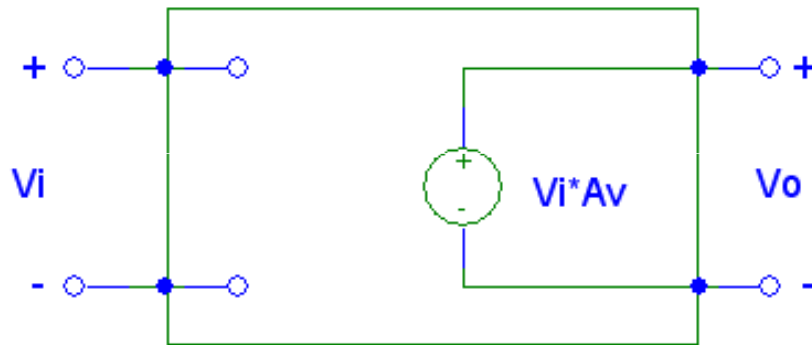
# Dependent sources

- Idea of amplification (gain)
  - V controlled V generators ( $A_v$ )
  - V controlled V generators ( $A_z$ )
  - V controlled I generators ( $G_m$ )
  - I controlled I generators ( $A_i$ )

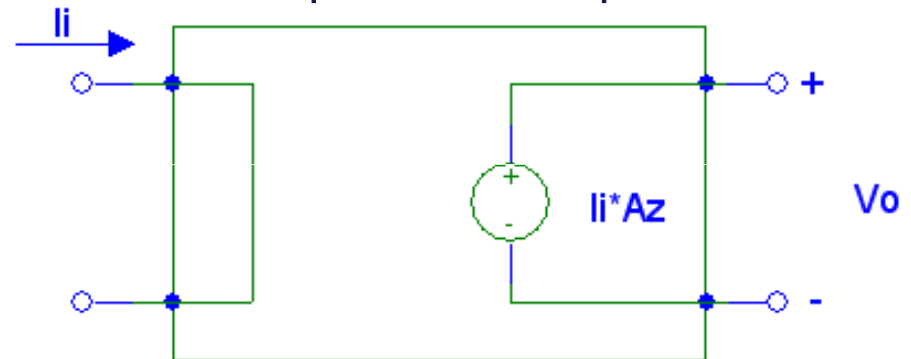


# Ideal amplifiers

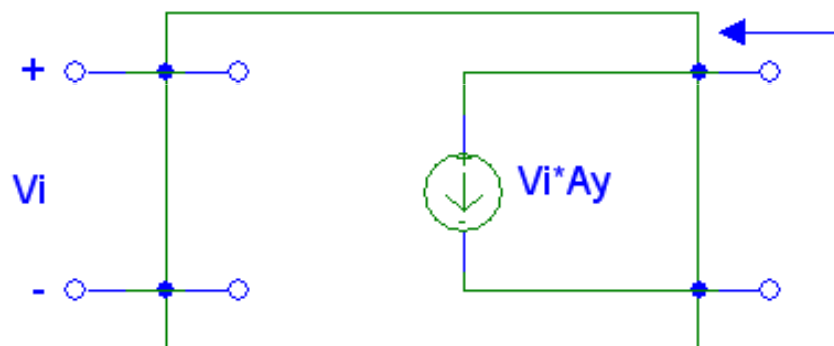
Voltage amplifier



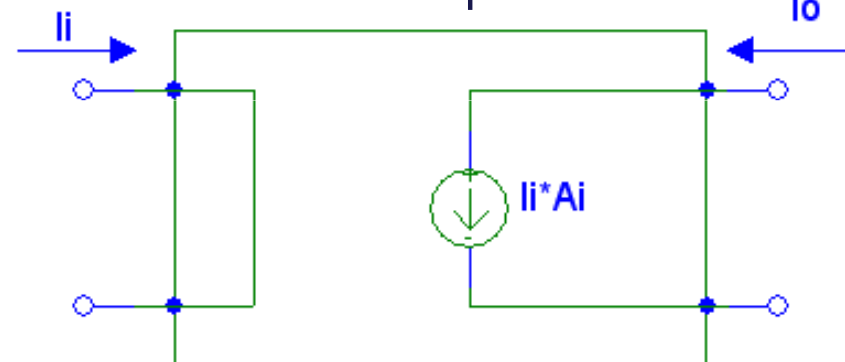
Transimpedance amplifier



Transconductance amplifier

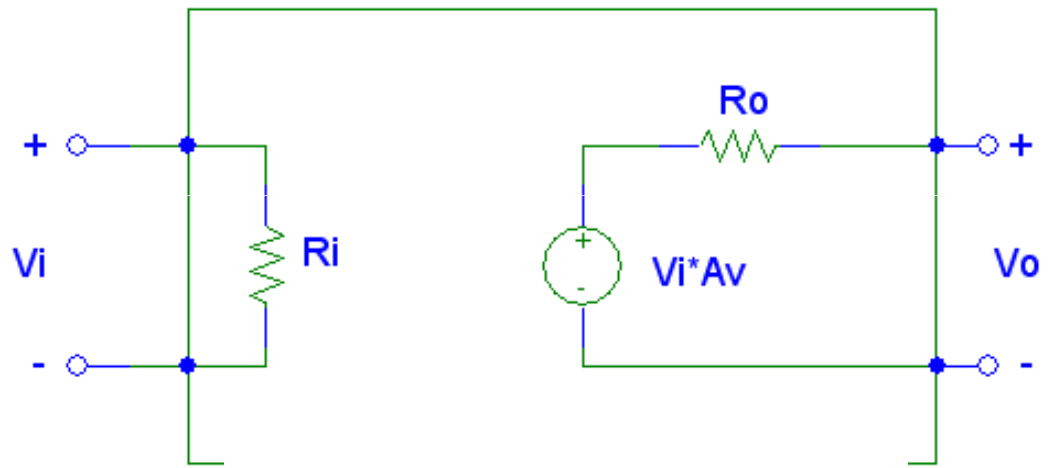


Current amplifier

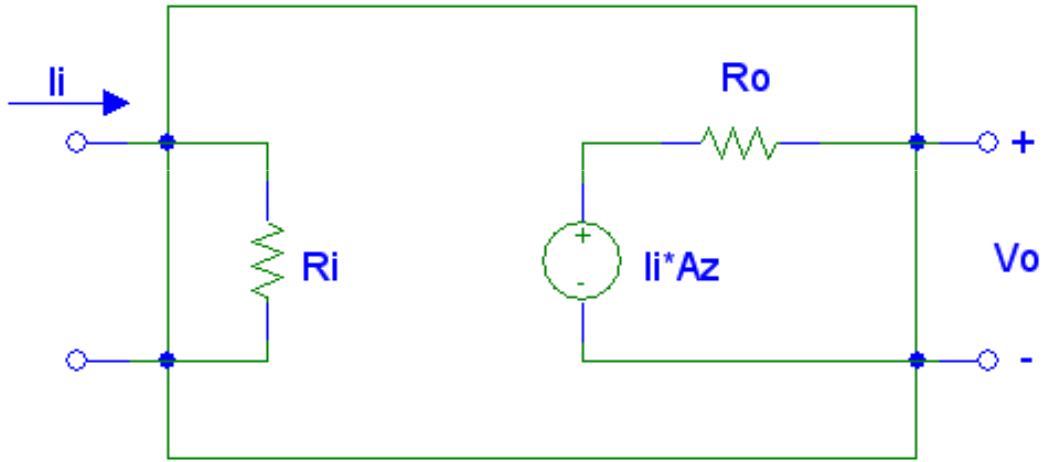


# Real Amplifiers

Voltage amplifier

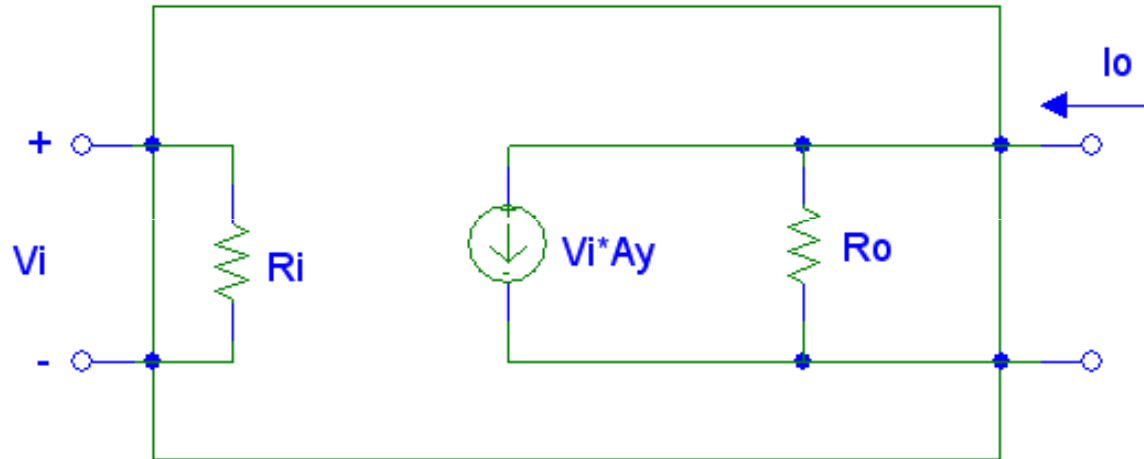


Transimpedance amplifier

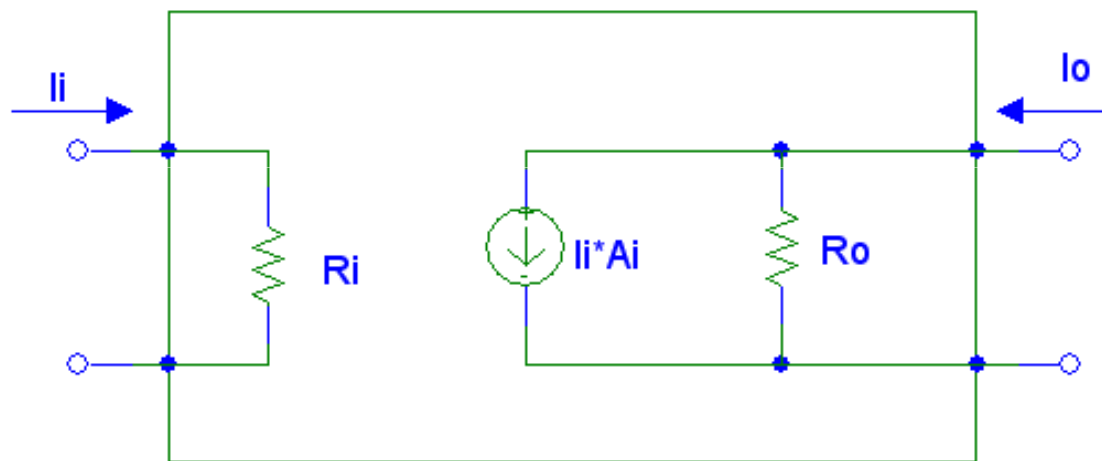


# Real Amplifiers

Transconductance amplifier

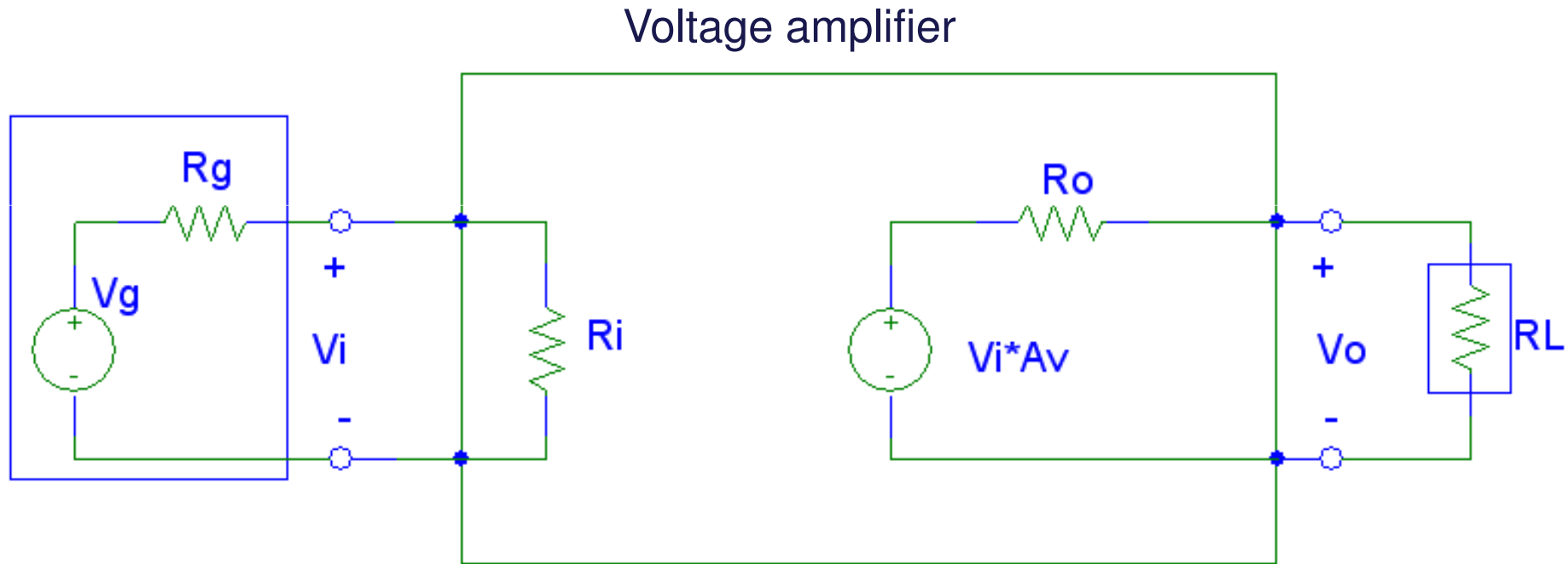


Current amplifier





# Loading Effects



Input Divider  $R_g - R_i$  ( $R_i$  input impedance)

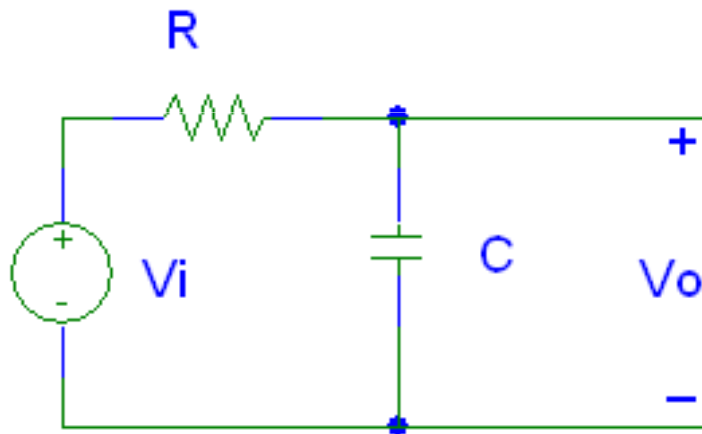
Divisor de salida  $R_L - R_o$  ( $R_o$  impedancia de salida)

$$V_o = A_v \cdot \frac{R_i}{R_i + R_g} \cdot \frac{R_L}{R_o + R_L} \cdot V_g$$

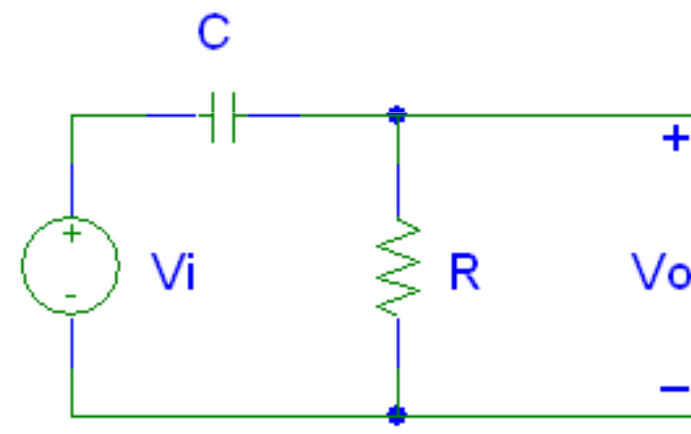
# Time and frequency response of RC circuits

- Continuous response
- Transient response (and pulses)
- Frequency Response

Low-pass network

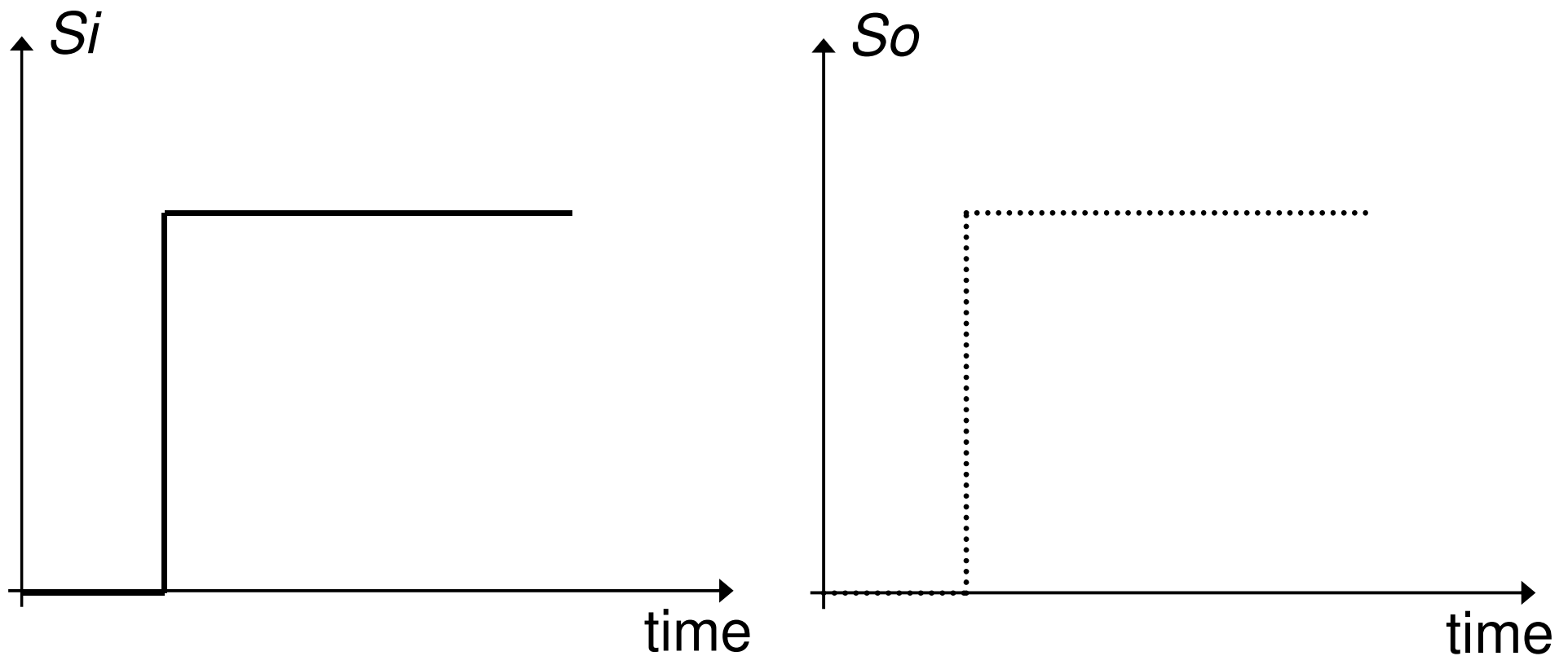


High-pass network

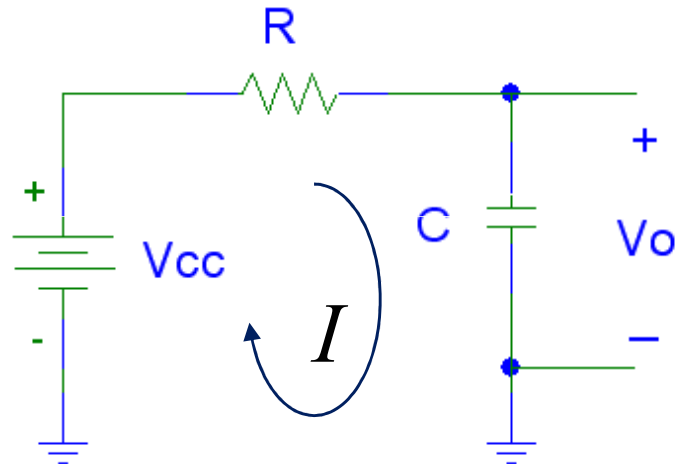


# Time response (1 st order)

*Plot the exponential response and point out the instant and amplitude after one time constant  $\tau_p$*

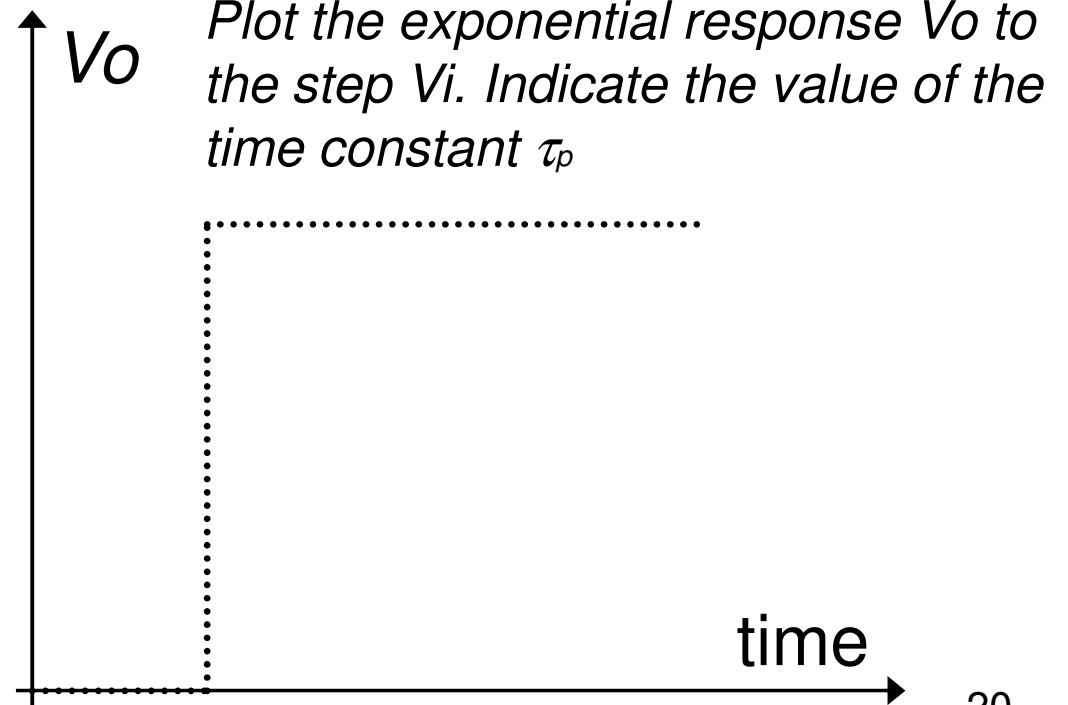
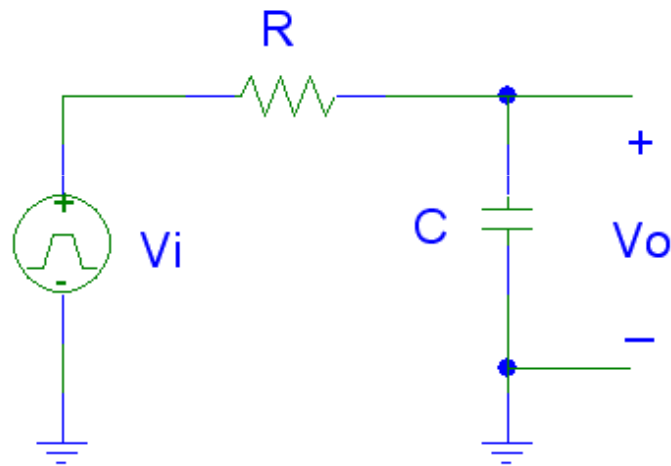


# RC circuit in DC and transient



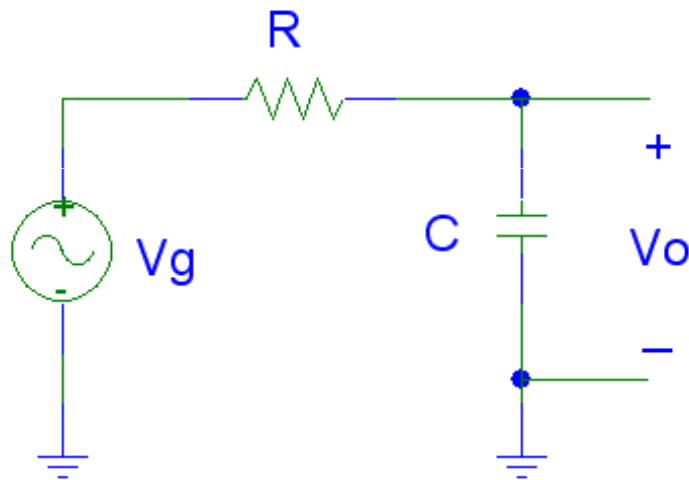
Calculate the current in the circuit and  $V_o$

$$I = 0 \Rightarrow V_o = V_{CC}$$



# RC circuit in AC (PSR)

## Frequency response



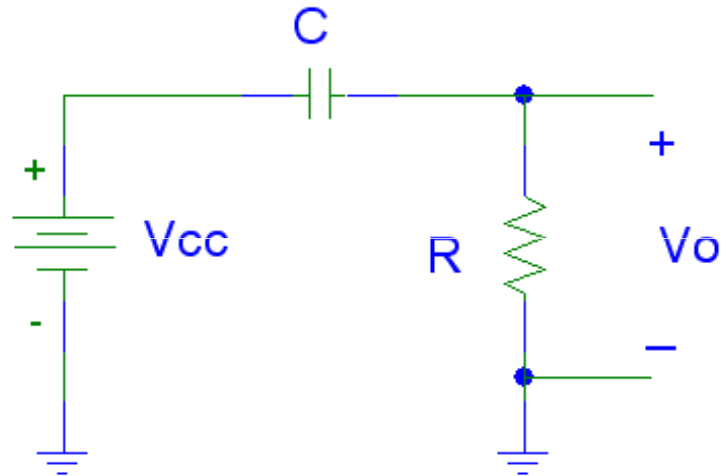
Get the transfer function  $V_0 / V_g$  in amplitude and phase.

$$V_0 = V_g \frac{Z_C}{R + Z_C} = V_g \frac{1}{1 + j\omega CR}$$

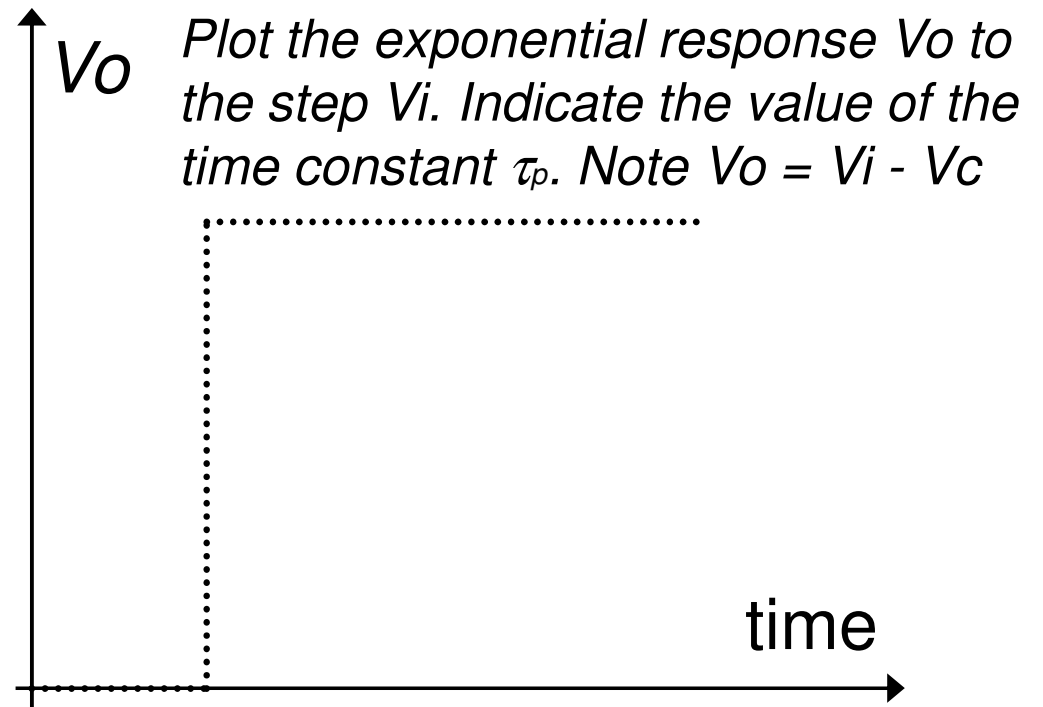
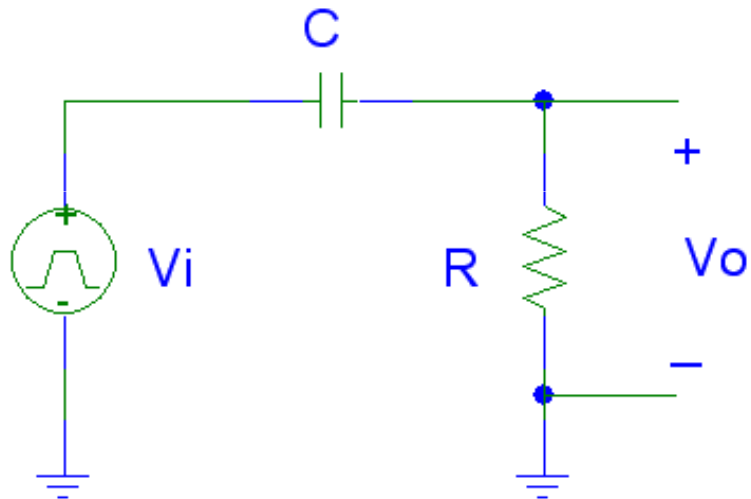
Calculate the amplitude and phase values when the frequency of  $V_g$  is:

$\left\{ \begin{array}{l} \omega 1 = 0 \\ \omega 2 = 1/(10 \cdot R \cdot C) \\ \omega 3 = 1/(R \cdot C) \\ \omega 4 = 10/(R \cdot C) \\ \omega 5 \rightarrow \infty \end{array} \right.$	$\left  \frac{V_0}{V_g} \right  = \frac{1}{\sqrt{1 + (\omega CR)^2}}$	$\left\{ \begin{array}{l} = 1 \\ \approx 1 \\ = \frac{1}{\sqrt{2}} \\ \approx \frac{1}{10} \\ = 0 \end{array} \right.$	$\angle V_0 - \angle V_g =$	$\left\{ \begin{array}{l} = 0 \quad (0^\circ) \\ \approx 0 \\ = -\pi/4 \quad (-45^\circ) \\ \approx -\pi/2 \\ = -\pi/2 \quad (-90^\circ) \end{array} \right.$				
					$- \arctg(\omega CR)$			

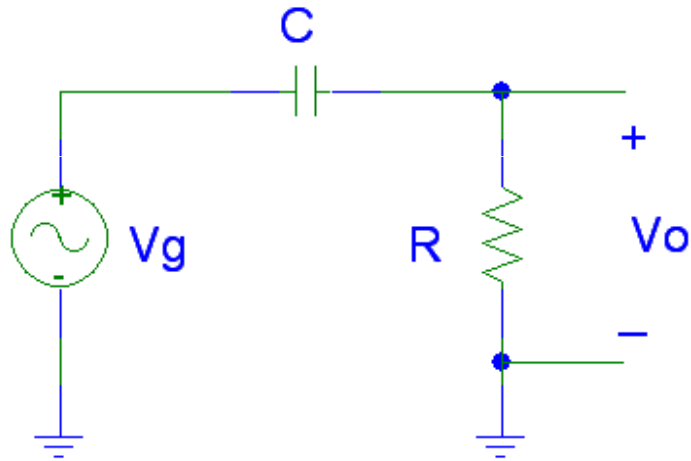
# RC circuit in DC and transient (II)



*Calculate the current in the circuit and  $V_o$*



# RC circuit in AC (RPS) Frequency Response (II)



Get the transfer function  $V_o / V_g$  in amplitude and phase.

Calculate the amplitude and phase values when the frequency of  $V_g$  is:

$$\omega_1 = 0$$

$$\omega_2 = 1/(10 \cdot R \cdot C)$$

$$\omega_3 = 1/(R \cdot C)$$

$$\omega_4 = 10/(R \cdot C)$$

$$\omega_5 \rightarrow \infty$$

# Frequency Response Diagrams (Bode)

