

Open kinematic chains (kinematics)

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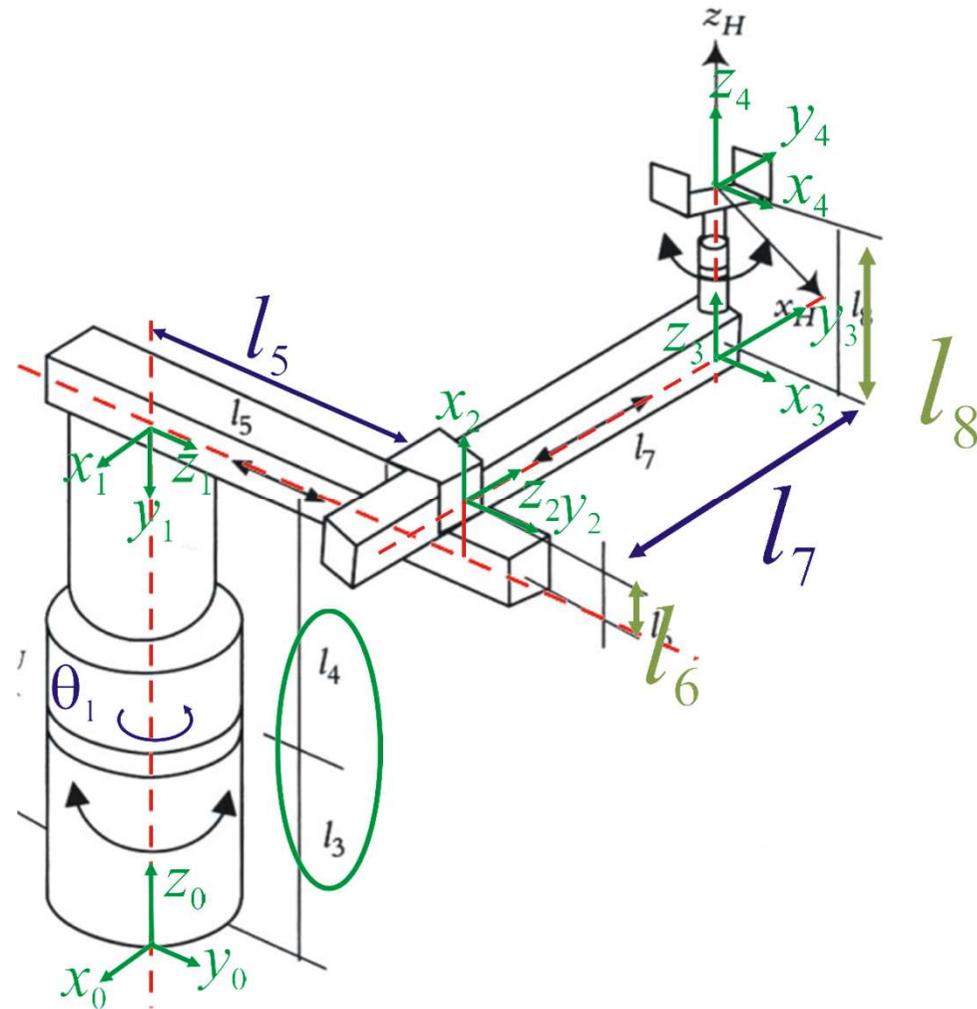


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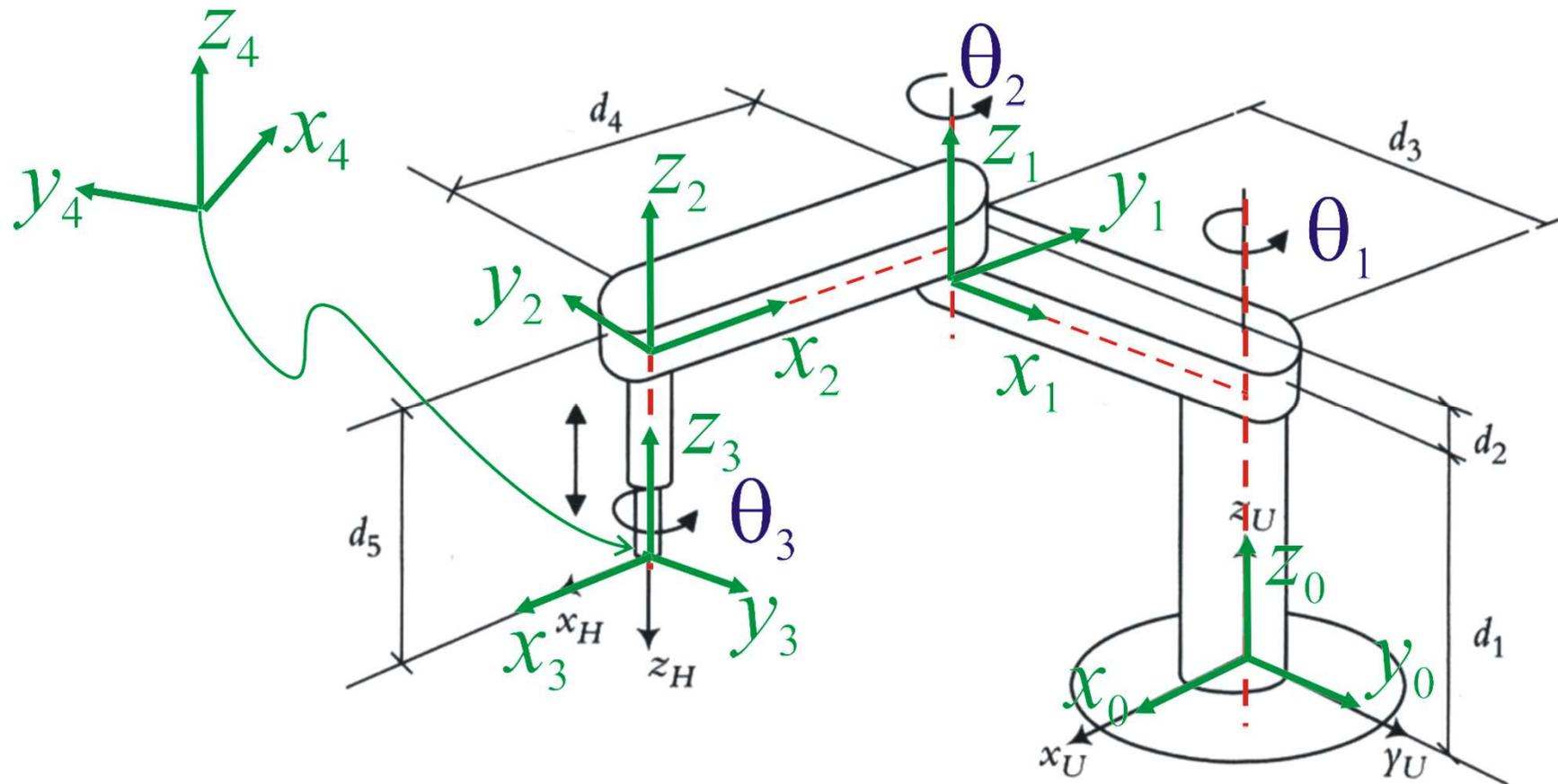


Problem 1





Problem 2





Problem 3

