



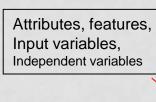


- The main goal of this lecture is threefold:
  - To describe the basic machine learning pipeline (the sequence of processes that are typically followed in Machine Learning).
  - To explain some basic concepts: instances, attributes, and instance space.
  - To describe two of the basic Machine Learning algorithms: Knearest neighbours and decision trees.

- About the KNN algorithm:
  - KNN is explained both for classication and regression.
  - Some of the advanges of KNN are explained (the main one being that it is not necessary to build an explicit model), and the inconveniences (slowness in classificating new instances, the problem with irrelevant attributes, the curse of dimensionality, and the problems with noise)
  - It is shown what the K means, its influence on classification and how to select it.
- About the decision tree algorithm:
  - The algorithm that builds decision trees is explained via an example
  - It is shown that the algorithm is recursive and basically amounts to choosing the best attribute at each node, by minimizing a measure called entropy.
  - It is shown how to extend the basic algorithm to regression tasks, via model trees and regression trees. In this case, the measure to minimize is variance, instead of entropy.

## BASIC MODELS: NEAREST NEIGHBOURS AND TREE-BASED MODELS

# Machine Learning Pipeline for classification (and regression)



Instances, examples

Label, class, output variable, dependent variable

Test data

Sky	Temperature	Humidity	Wind	Tennis
Sunn	85	85	No	No
Sunn	80	90	Yes	No
Outc ast	83	86	No	Yes
Rainy	70	96	No	So
Rainy	68	80	No	Yes
Outc ast	64	65	Yes	Yes
Sunn	72	95	No	No
Sunn	69	70	No	Yes
y Rainy	75	80	No	Yes
Sunn	75	70	Yes	Yes
Outc ast	72	90	Yes	Yes
Outc ast	81	75	No	Yes
Rainy	71	91	Yes	No

Sky	Tempe rature	Humidity	Wind	Tennis
Sunny	60	65	No	?????

ML Algorithm

**IF** Sky = Sunny **AND** Humidity <= 75

**THEN** Tennis = Yes ...



Model (Classifier)

Class = Yes

Prediction

**Training Data** 

#### DEFINITIONS: ATTRIBUTES AND LABEL

#### Attributes / features

- A feature is an individual measurable property of an instance, represented as a number
- Types:
  - In general, real numbers:
    - 0, 1, 2
    - 1.3, 7.9, 10.798, ...
  - Categorical: red / green / yellow
  - Ordinal: cold, lukewarm, hot
    - Typically, they are encoded as integer numbers

#### Class / label

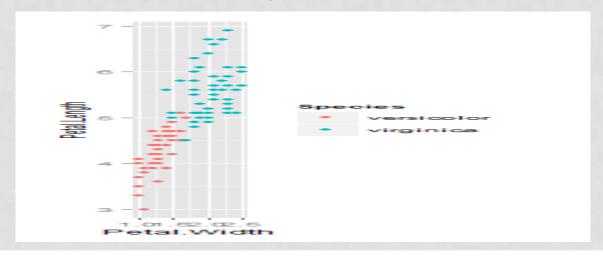
- If categorical (e.g. cancer / no cancer) => classification problem
- If real / integer number => regression problem

#### **DEFINITIONS: INSTANCE SPACE**

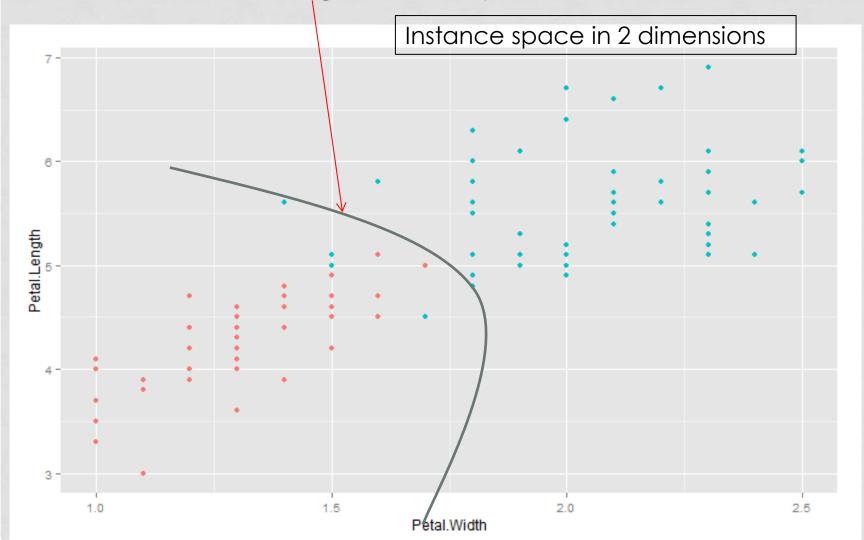
- Instances, examples, = tuples
  - In general, they inhabit a d-dimensional space (instance space)
  - (input, output) =  $(\mathbf{x}_{i}, y) = (x_{i1}, x_{i2}, ..., x_{id}, y) \in (\mathbf{R}^{d}, Y)$ 
    - Note: boldface means vector
    - This instance has 4 inputs and 1 output. It inhabits a 4-dimensional space

Sky	Temperature	Humidity	Wind	Tennis
X <sub>1</sub>	$x_2$	<b>X</b> <sub>3</sub>	<b>X</b> <sub>4</sub>	у
Sunny	60	65	No	Yes

In 2-dimensions (2 attributes), each instance is a point in instance space

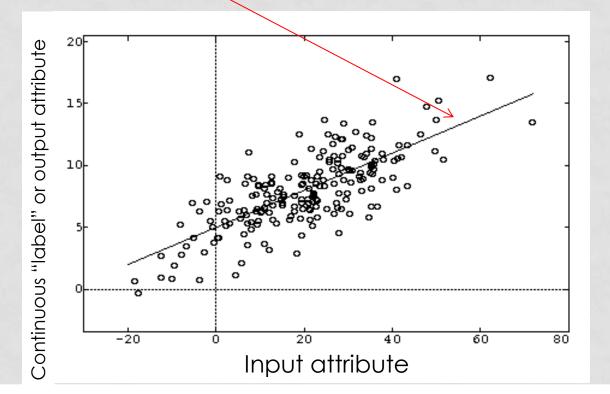


- Example: classify plants into two classes ("versicolor" / red vs.
   "virginica" / blue)
- 2 attributtes = (Petal.Width, Petal.Length) = 2 dimensions
- Classification = finding a boundary between the classes

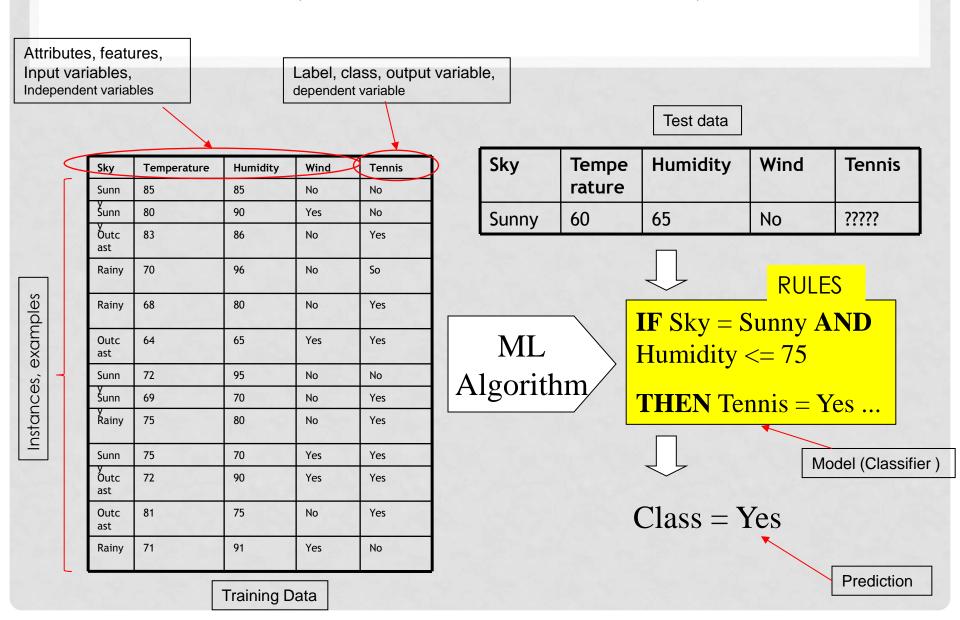


#### INSTANCE SPACE IN REGRESSION

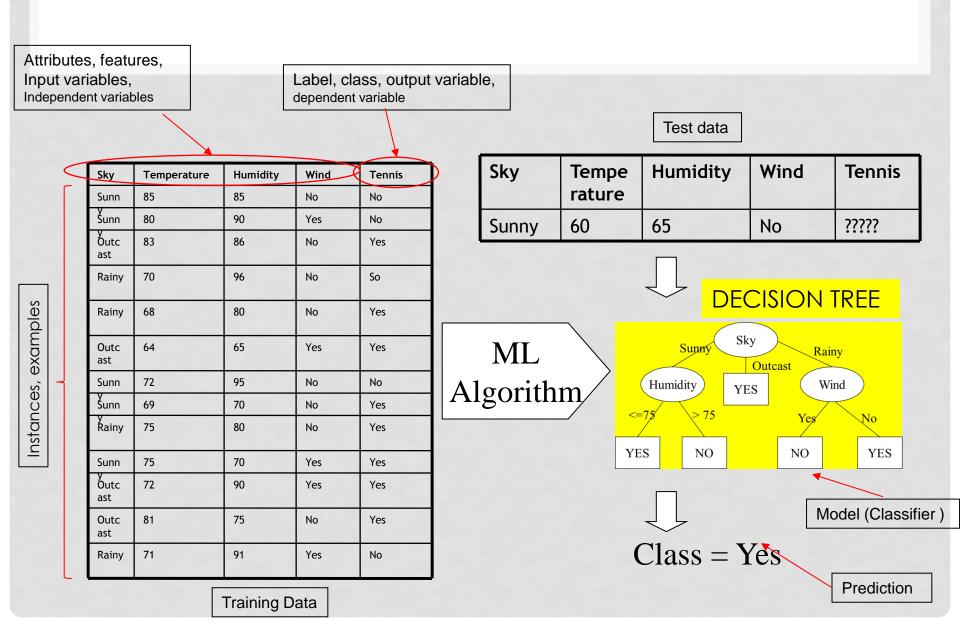
- In the following case, there is one input variable and an output variable (continuous "label")
- Regression = finding a function that transforms the inputs into the output



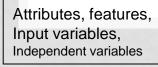
## MODELS (CLASSIFICATION): RULES



#### MODELS: DECISION TREES



#### MODELS: MANY OTHERS



Instances, examples

Label, class, output variable, dependent variable

Test data

Sky	Temperature	Humidity	Wind	Tennis
Sunn	85	85	No	No
Sunn	80	90	Yes	No
Outc ast	83	86	No	Yes
Rainy	70	96	No	So
Rainy	68	80	No	Yes
Outc ast	64	65	Yes	Yes
Sunn	72	95	No	No
Sunn	69	70	No	Yes
y Rainy	75	80	No	Yes
Sunn	75	70	Yes	Yes
Outc ast	72	90	Yes	Yes
Outc ast	81	75	No	Yes
Rainy	71	91	Yes	No

Sky	Tempe rature	Humidity	Wind	Tennis
Sunny	60	65	No	?????



ML Algorithm

- Nearest neighbor
- Ensembles (bagging, boosting, stacking, ...)
- Functions: neural networks, support vector machines, deep learning, ...
- Naive bayes, bayesian networks



Model (Classifier)

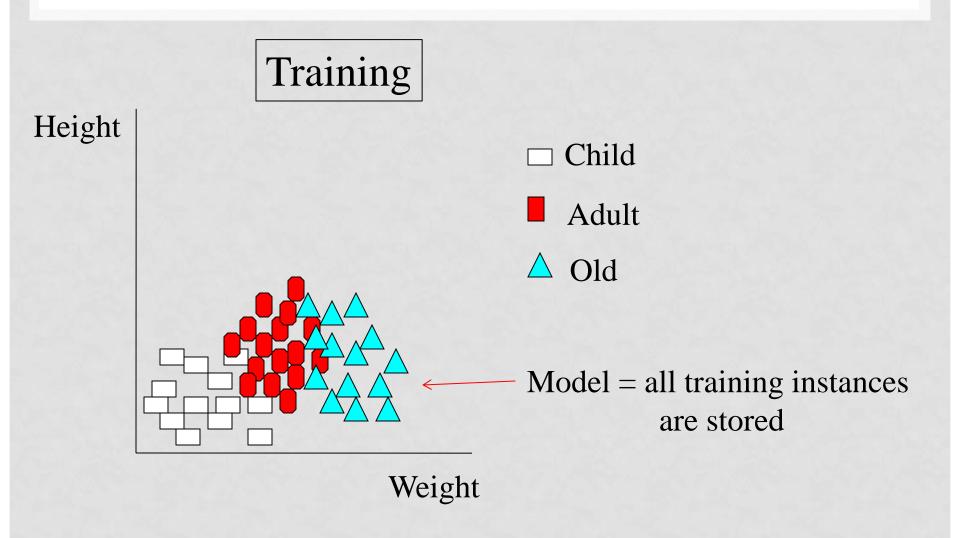
Class = Yes

Prediction

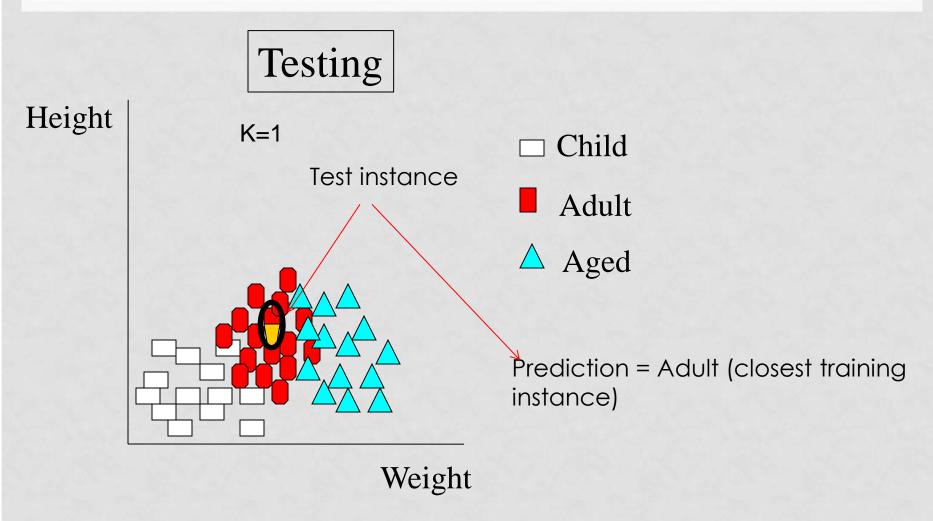
**Training Data** 

# KNN: K-NEAREST NEIGHBOURS

#### K-NEAREST NEIGHBORS (KNN)

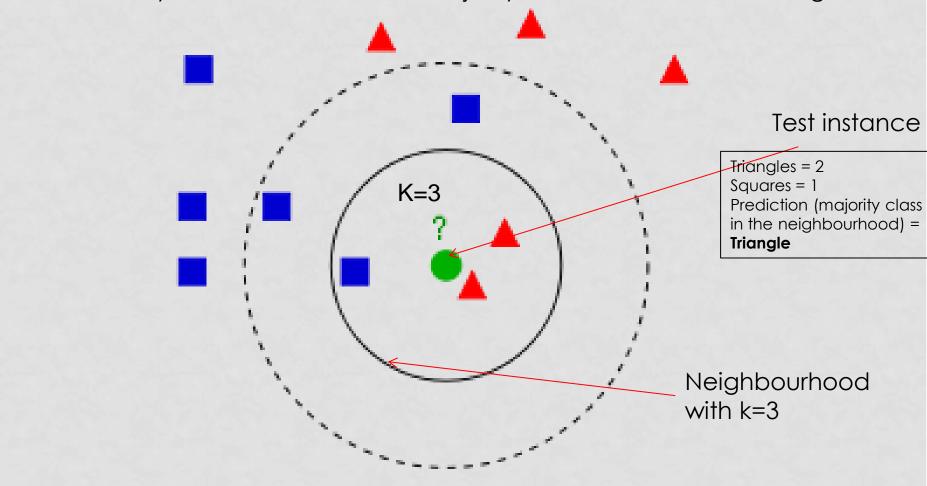


#### K-NEAREST NEIGHBORS (KNN)

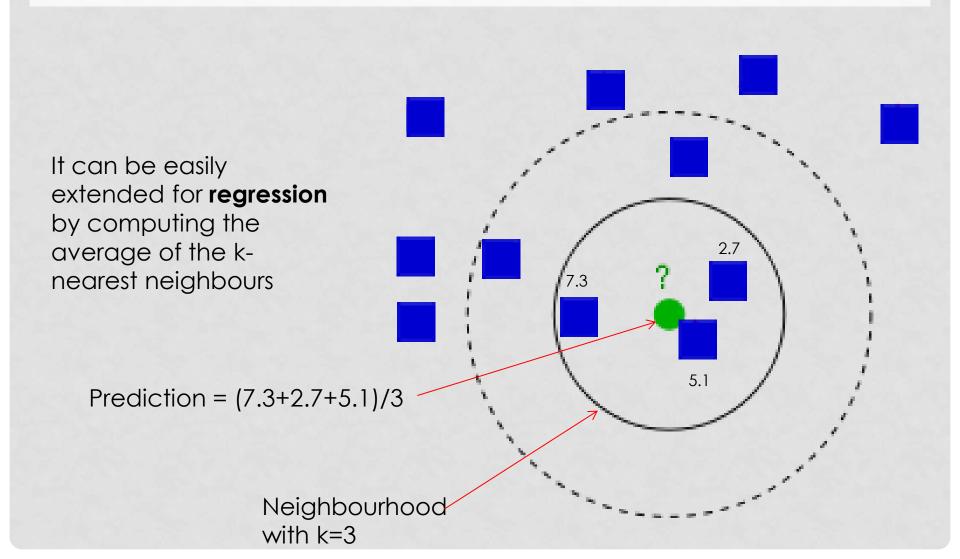


#### K-NEAREST NEIGHBORS (KNN)

K> 2 => classify new instances as the majority class of the k-nearest neighbours

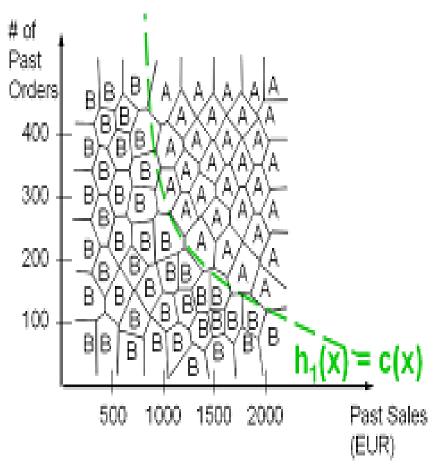


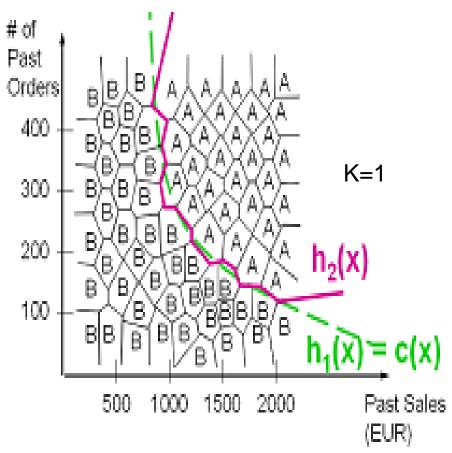
#### KNN FOR REGRESSION



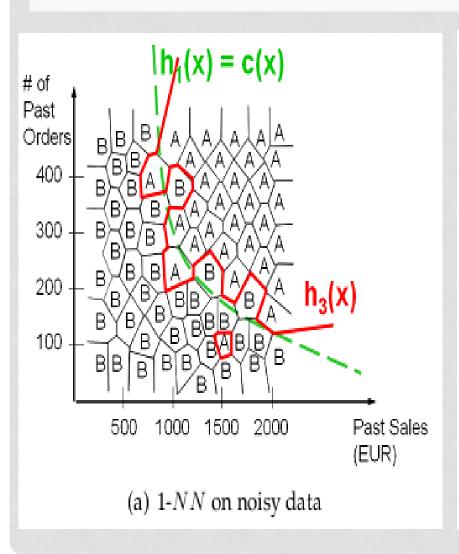
#### WHY USE K>1?

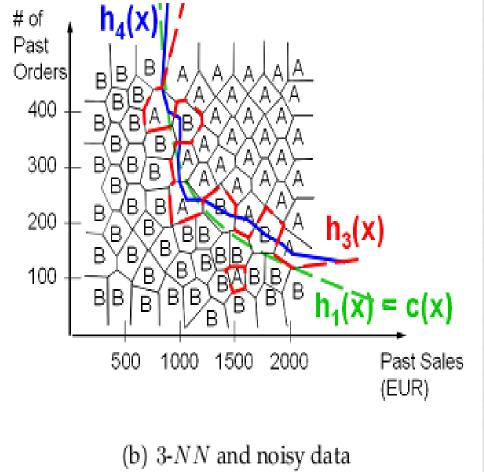
#### **VORONOI TESSELLATION in Instance space**





#### WHY USE K>1?





#### WHY USE K>1?

- With k=1, noisy instances (i.e. class overlap) have a large influence
- With k>1, more neighbors are considered and noisy instances have less influence (it is like averaging)
- But if k is very large, locality is lost
  - What is KNN if k=number of instances?
- If the number of classes is two, use odd k in order to avoid draws
- K is a parameter of the algorithm (a hyperparameter, actually) and the correct value has to be found out.
   Hyperparameter tuning is part of the ML pipeline, and we will talk about it in future lectures

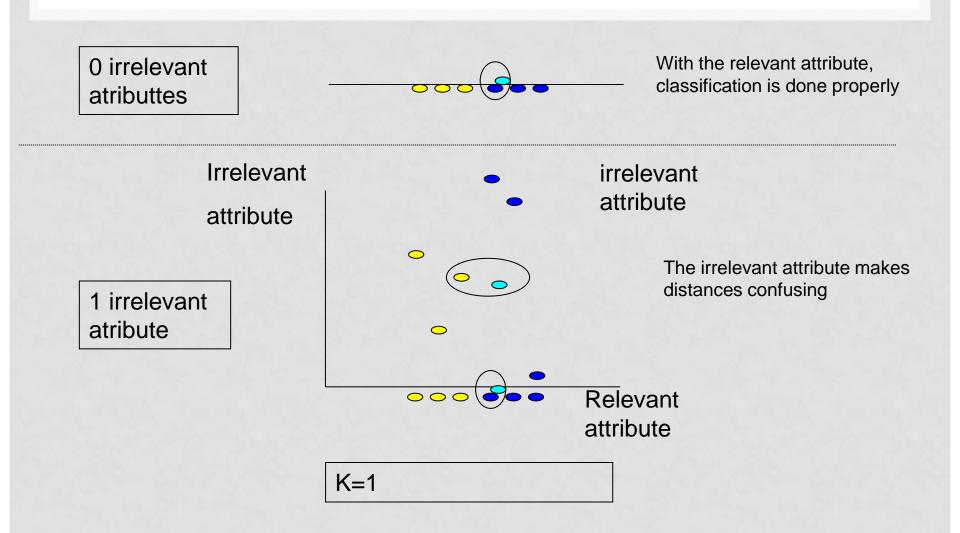
#### SUMMARY OF KNN

- KNN classifies test instances as the majority class in the neighbourhood of the training set
- KNN is a lazy ML algorithm
  - During training, no model is constructed, but all training instances are stored (model = training instances)
- It is based on the idea that the best model of data is the data itself
- It can be easily extended for regression by computing the average of the k-nearest neighbours

#### LIMITATIONS OF KNN

- Slow (when testing): all distances to each training instance must be computed
- Large storage requirements (all training data is stored)
- Very sensitive to irrelevant attributes and the curse of dimensionality

#### Irrelevant attributes



#### **DISTANCES**

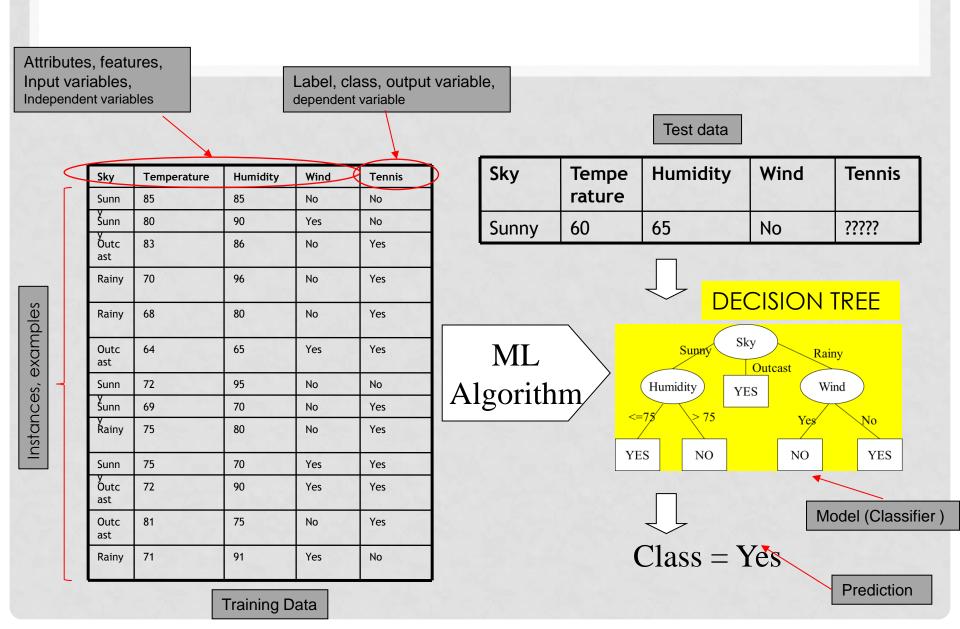
- For numerical attributes, use the Euclidean distance:
  - 2D:  $d(\mathbf{x_i}, \mathbf{x_j})^2 = (x_{i1} x_{j1})^2 + (x_{i2} x_{j2})^2$ 
    - $d(\mathbf{x_i}, \mathbf{x_j}) = \sqrt{((x_{i1}-x_{j1})^2 + (x_{i2}-x_{j2})^2)}$
  - dD:  $d(\mathbf{x_i}, \mathbf{x_j})^2 = (x_{i1} x_{j1})^2 + (x_{i2} x_{j2})^2 + ... + (x_{id} x_{jd})^2$
- For nominal / categorical attributes, use the Hamming distance:
  - If attribute e es nominal (discrete, categorical, ...), instead of  $(x_{ie}-x_{je})^2$ , the following is used:  $\delta(x_{ie},x_{je})$ : 0 if  $x_{ie}=x_{je}$  and 1 otherwise
- or transform the attribute to dummy variables / onehot encoding)

#### **NORMALIZATION**

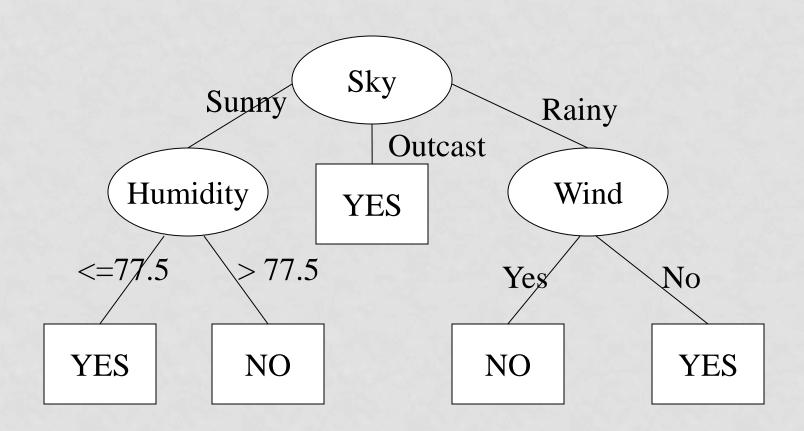
- It is important to normalize attributes, because ranges can be different (e.g. human body temperature ranges from 35° to 45° celsius, body height ranges from 0 to 2m, age ranges from 0 to 100 years, etc.)
- Otherwise, attributes with a large range have more weight on the distance
- Normalizing to 0-1 range:
  - $x'_{1j} = (x_{1j} \min_j) / (\max_j \min_i)$

# MODELS: DECISION TREES (AND RULES) FOR CLASSIFICATION AND REGRESSION

#### MODELS: DECISION TREES



#### Decision trees



#### Algorithms for building decision trees

- The most basic is ID3: decision trees are constructed recursively from the root to the leaves, each time selecting the best node (attribute) to put on the tree
- C4.5 (or J48), is able to deal with continuous attributes and uses statistical criteria to prevent overfitting the tree to the data (too large trees imply that data is memorized rather than generalized)

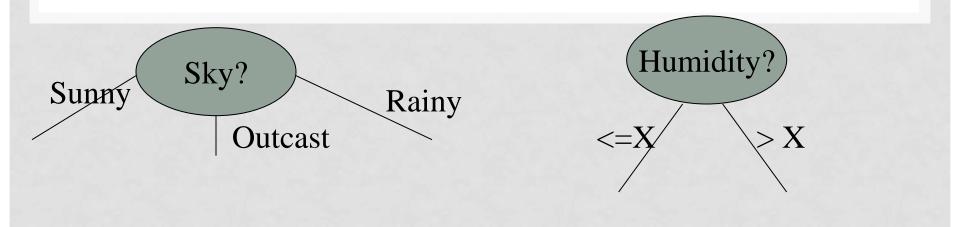
## Simplified ID3 algorithm

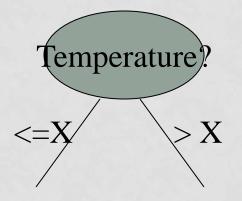
- 1. Stop growing the tree if:
  - 1. All examples belong to the same class
  - 2. If there are no remaining instances or attributes
- Otherwise, select the best attribute for that node, according to some criteria (entropy minimization, for instance)
- 3. Build recursively as many subtrees as values in the selected attribute

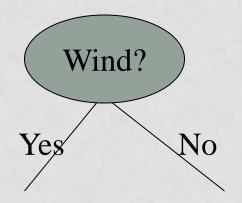
## Simplified C4.5 algorithm

- 1. Stop growing the tree if:
  - 1. All examples belong to the same class
  - 2. If there are no remaining instances or attributes
  - 3. If no improvements are expected by growing the tree
- 2. Otherwise, select the best attribute for that node, according to some criteria (entropy minimization, for instance)
- 3. Build recursively as many subtrees as values in the selected attribute

## WHAT IS THE BEST NODE TO PUT IN THE ROOT OF THE TREE?







## Let's try with attribute SKY

Sky generates as many partitions as values (3: sunny,

outcast, rainy)

Sunny
Outcast

Sky

S	T	H	V	Ten
Sun ny	85	85	No	No
Sun ny	80	90	Yes	No
Sun ny	72	95	No	No
Sun ny	69	70	No	Yes
Sun ny	75	70	Yes	Yes

"3 No, 2 Yes"

"no" majority

S	T	Н	W	Ten
Outcast	83	86	No	Yes
Outcast	64	65	Yes	Yes
Outcast	72	90	Yes	Yes
Outcast	81	75	No	Yes

"0 No, 4	Yes"
•	

Perfect partition
-------------------

S	T	Н	W	Ten	
Rainy	70	96	No	Yes	
Rainy	68	80	No	Yes	
Rainy	75	80	No	Yes	
Rainy	65	70	Yes	No	
Rainy	71	91	Yes	No	

Rainy

"2 No, 3 Yes"



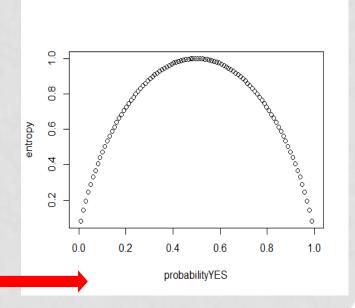
### How do we know if SKY is a good attribute?

- Perfect partition:
  - 0% No, 100% Yes
  - 100% No, 0% Yes
- Worse partition: 50% No, 50% Yes
- Entropy measures partition quality (the larger, the worse)

$$H(P) = -\sum_{C_i} p_{C_i} \log_2(p_{C_i})$$

$$H(P) = -(p_{yes} \log_2(p_{yes}) + p_{no} \log_2(p_{no}))$$

$$p_{no} = (1 - p_{yes})$$



Proportion of Yes

# OTHER WAYS TO MEASURE PARTITION QUALITY

Entropy

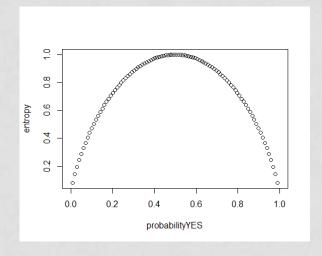
$$H(P) = -\sum_{Ci} p_{Ci} \log_2(p_{Ci})$$

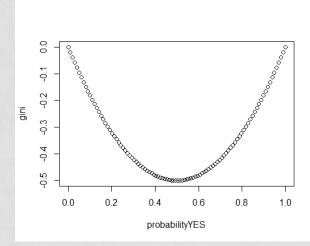
Gini

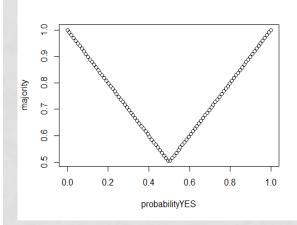
$$Gini(P) = -\sum_{Ci} p_{Ci} (1 - p_{Ci})$$

Majority

$$M(P) = \max(p_{yes}, p_{no})$$







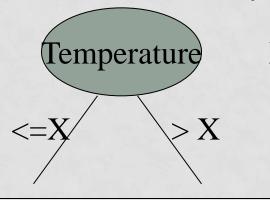
### Average entropy for Sky

- Entropy for the three partitions of Sky:
  - 1. "3 No, 2 Yes":  $H=-((3/5)*log_2(3/5)+(2/5)*log_2(2/5)=0.97$
  - 2. "0 No, 4 Yes":  $H=-((0/4)*log_2(0/4)+1*log_2(1))=0$
  - 3. "2 No, 3 Yes":  $H=-((2/5)*log_2 (2/5)+(3/5)*log_2 (3/5))=0.97$
- Average Sky entropy:
  - HP=(5/14)\*0.97+(4/14)\*0+(5/14)\*0.97 = 0.69
  - Note: there are 14 instances in the data set

## WHAT TO DO FOR CONTINUOUS ATTRIBUTES?

C4.5 creates a binary (two-values) attribute by computing a threshold X

Nota: only some thresholds are shown. The best one is X=84 with average entropy = 0.83



64 – Yes, 65-No, 68 – Yes, 69 – Yes, 70 – Yes, 71 – No, 72 – YesNo, 75 – YesYes, 80 – No, 81 – Yes, 83 – Yes, 85 - No

HP = 0.83

4 No, 9 Yes

1 No, 0 Yes

64 – Yes, 65-No, 68 – Yes, 69 – Yes, 70 – Yes, 71 – No, 72 – YesNo, 75 – YesYes, 80 – No, 81 – Yes, 83 – Yes, 85 - No

X=71.5

X = 70.5

HP = 0.93

2 No. 4 Yes

3 No, 5 Yes

64 – Yes, 65-No, 68 – Yes, 69 – Yes, 70 – Yes 71 – No, 72 – YesNo, 75 – YesYes, 80 – No, 81 – Yes, 83 – Yes, 85 - No

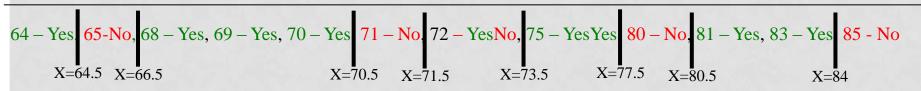
1 No, 4 Yes

4 No, 5 Yes

HP = 0.89

### Possible thresholds

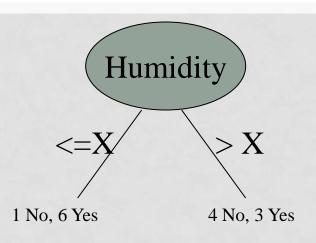
Possible thresholds are transitions from Yes to No, or from No to Yes:



- The actual threshold may depend on the algorithm implementation. Some implementations use the average: Ej: 64.5 = (64+65)/2.
- Other implementations use the maximum of the left partition. In that case, the possible thresholds would have been:

 Notice that entropy computed with the training data is the same in both cases, because in the two cases data is partitioned in the same way.

# Humidity



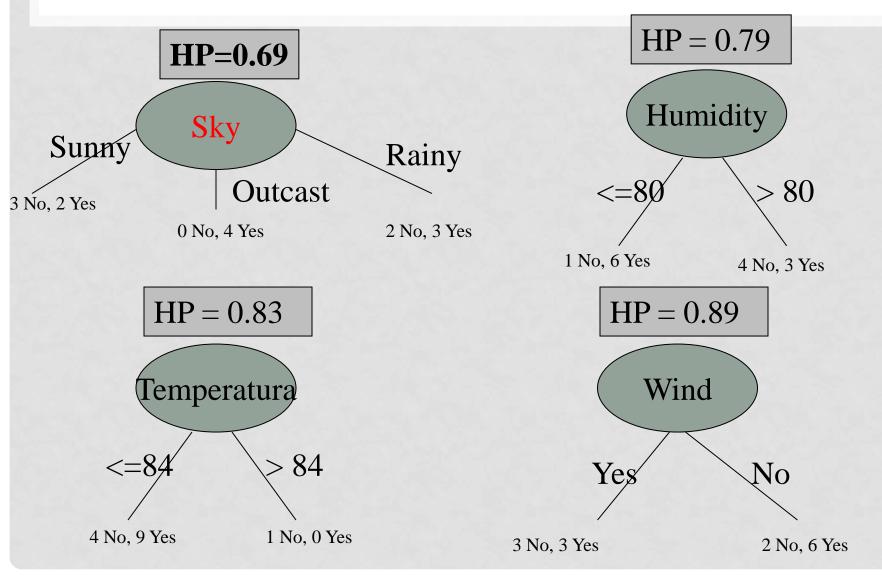
1 No, 6 Yes

4 No, 3 Yes

HP = 0.79

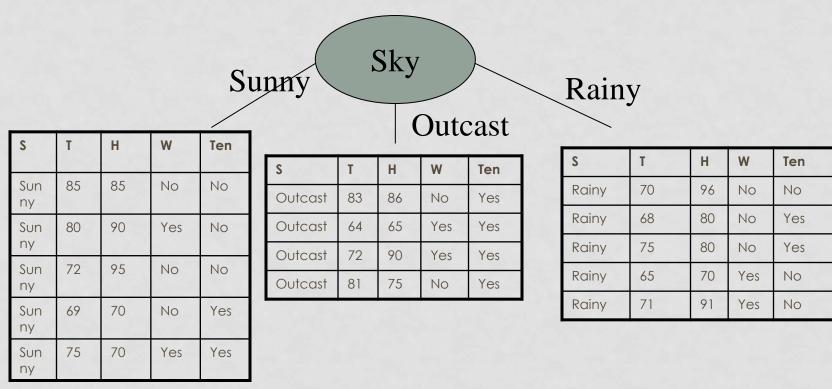
Note: there are other alternatives for the threshold, but this is the best one (minimum entropy)

# WHAT IS THE BEST NODE TO PUT IN THE ROOT OF THE TREE?



# Recursive tree growth

Now that the attribute for the root node has been determined, the process continues recursively. Now, the algorithm has to construct three new subtrees.



"3 No, 2 Yes"

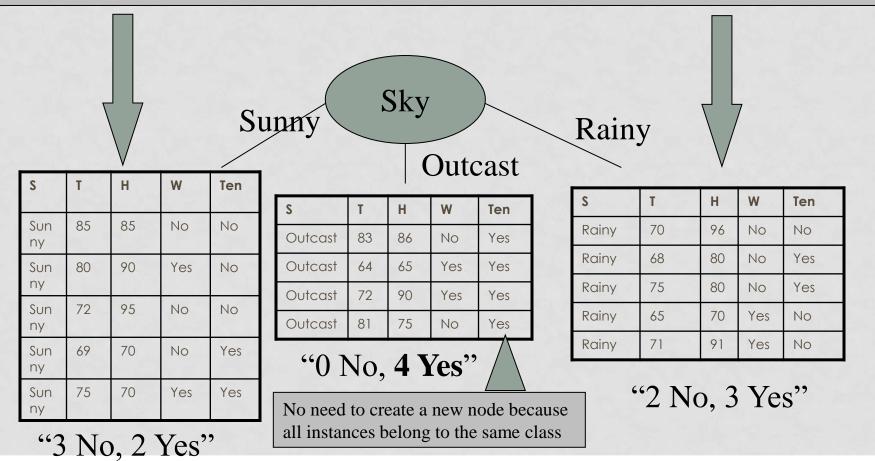
"0 No, 4 Yes"

"2 No, 3 Yes"

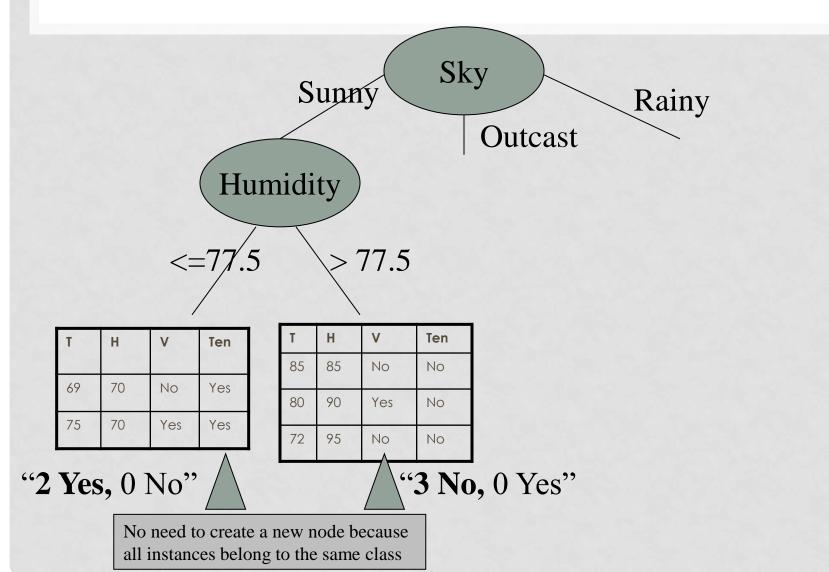
# When to stop splitting data?

What is the best option, continue splitting, or classify with the majority class (No).

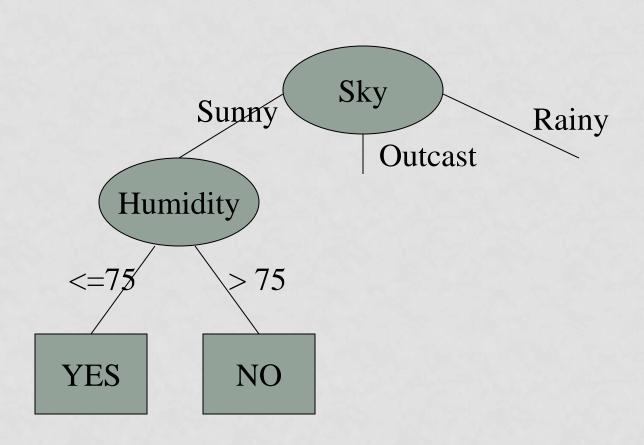
Use a statistical test. The decision might be based in too few instances.



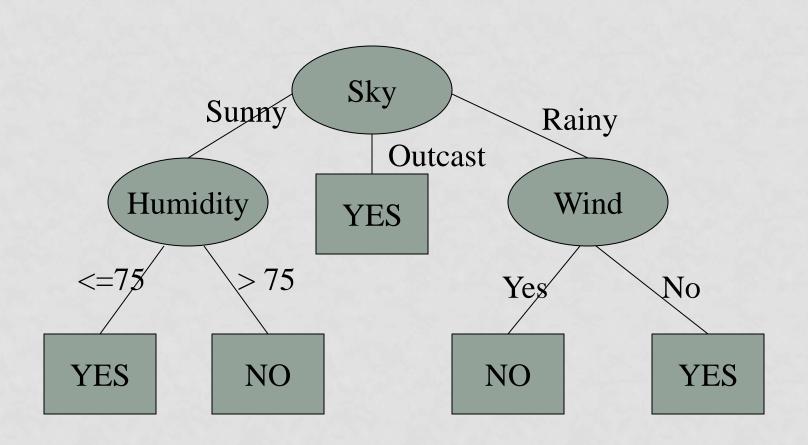
# Why stop tree growth?



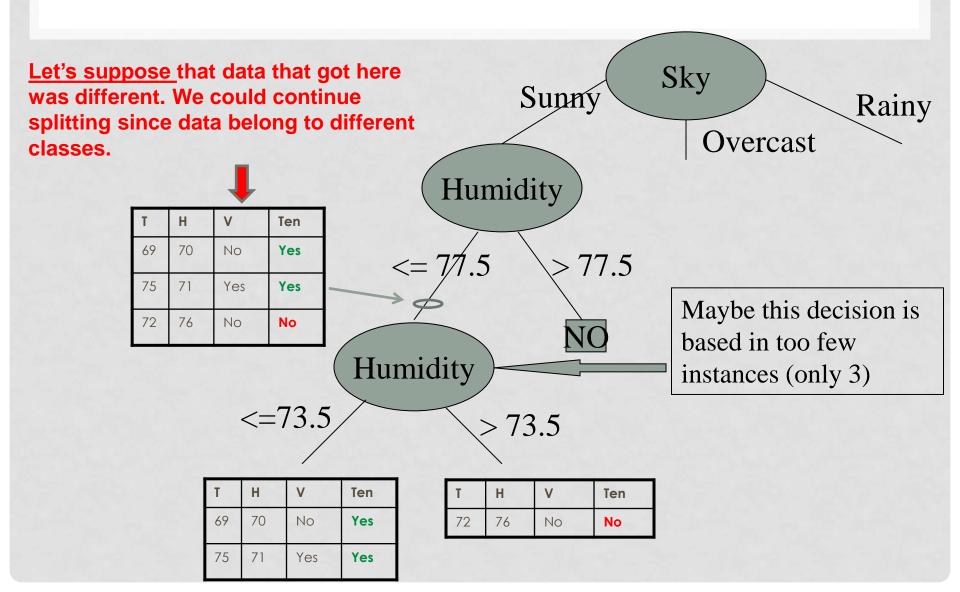
# Recursive tree growth



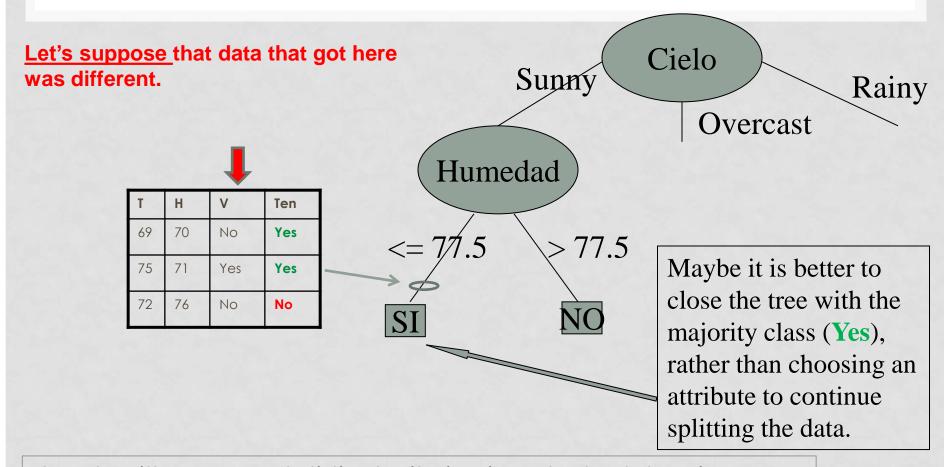
# Recursive tree growth



# Why to stop tree growth?



# Why to stop tree growth?



The algorithm uses a statistical criterion in order to determine whether it is worth to continue tree growth, whether the sample is too small, etc.

## Rules (created from the decision tree)

Obtain one rule from each path from the root to the leaves

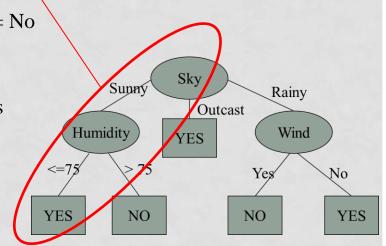
**○IF** Sky = Sunny **AND** Humidity <= 75 **THEN** Tennis = Yes

**ELSE IF** Sky = Sunny AND Humidity > 75 **THEN** Tennis = No

**ELSE IF** Sky = Outcast **THEN** Tennis = Yes

**ELSE IF** Sky = Rainy AND Wind = Yes **THEN** Tennis = Yes

**ELSE** Tennis = No

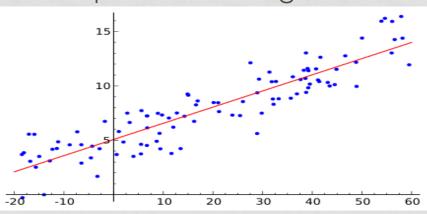


But there are algorithms that build rules directly from data

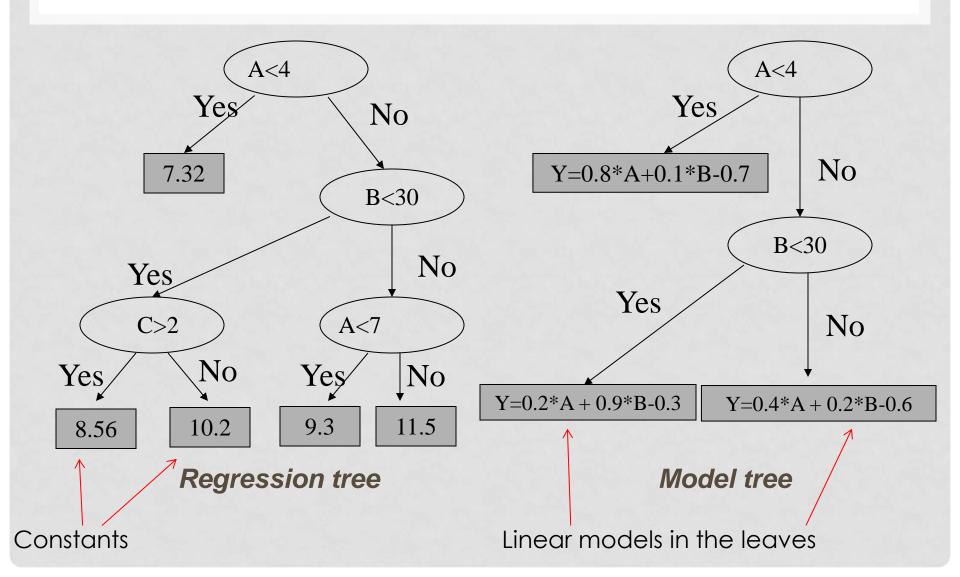
### TREES FOR REGRESSION

- What to do if the class / label is continuous (rather than discrete?
  - Answer: variance reduction (instead of entropy reduction)
- Two types:
  - Model trees
  - Regression trees

#### Example of linear regression



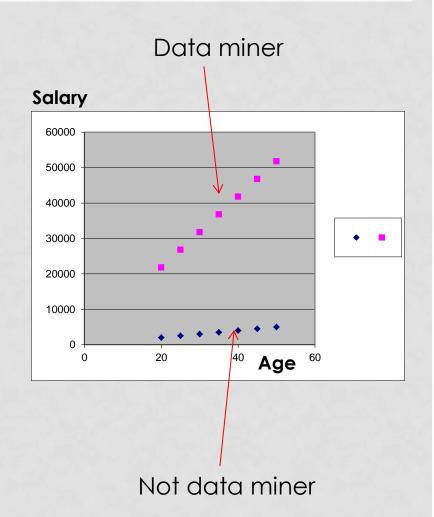
### TREES FOR REGRESSION: TWO TYPES



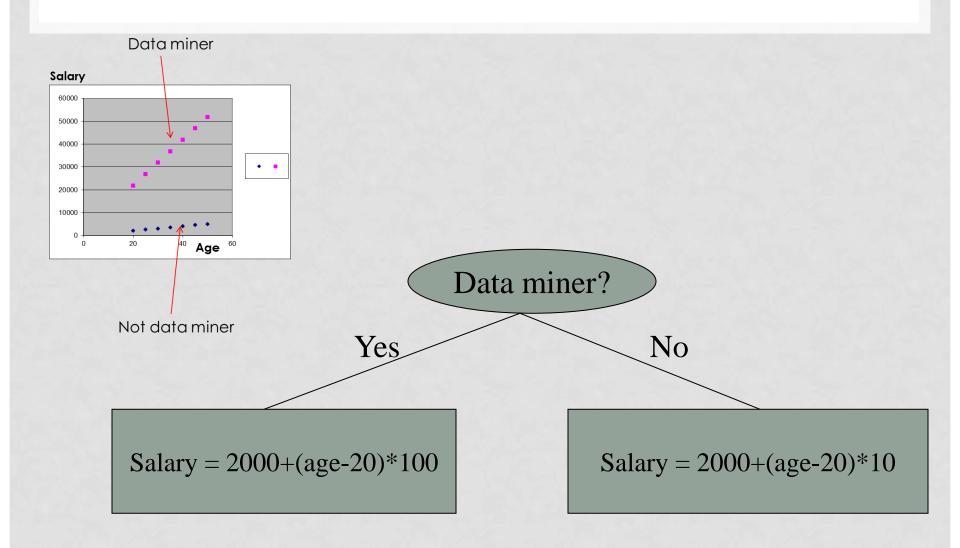
### **EXAMPLE**

#### Training data

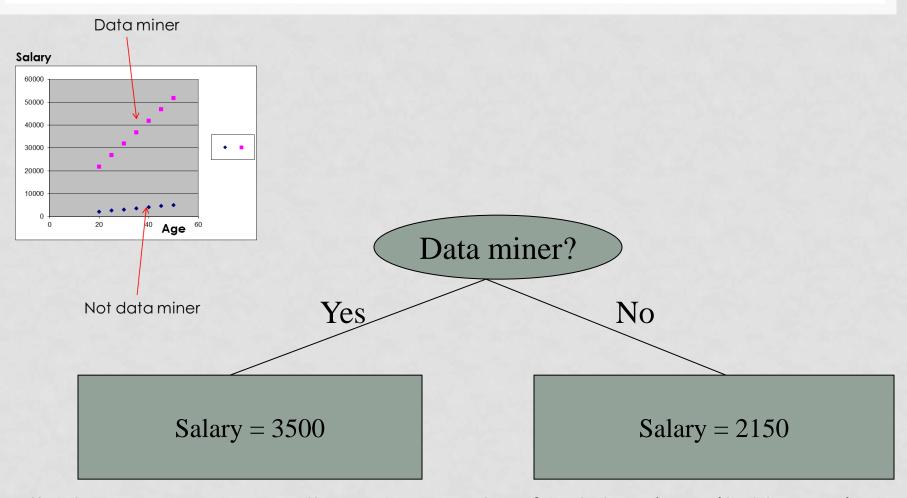
Data Miner?	Age	Salary
Yes	20	2000
Yes	25	2500
Yes	30	3000
Yes	35	3500
Yes	40	4000
Yes	45	4500
Yes	50	5000
No	20	2000
No	25	2050
No	30	2100
No	35	2150
No	40	2200
No	45	2250
No	50	2300



### MODEL TREES. EXAMPLE



### REGRESSION TREES. EXAMPLE



In the leaves, we can see the average salary for data miners (3500 euros) and the average salary for non-data miners (2150 euros)

### TREES FOR REGRESSION

- Regression and model trees are built similarly, except that in the leaves
  - For regression trees, the average output value is computed
  - For model trees, a linear model is constructed (M5 (Quinlan, 93))
- Trees for regression are built similarly than trees for classification (decision trees), except that **standard deviation** is reduced (instead of entropy)
- The tree is built recursively until a stopping condition is reached:
  - Too few examples (2)
  - Standard deviation smaller than 5% of the original sd

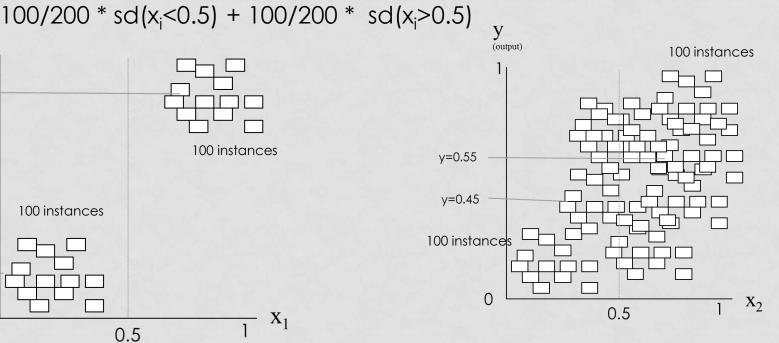
## WHAT IS THE BEST NODE TO PUT IN THE ROOT OF THE TREE?

Which attribute is better?

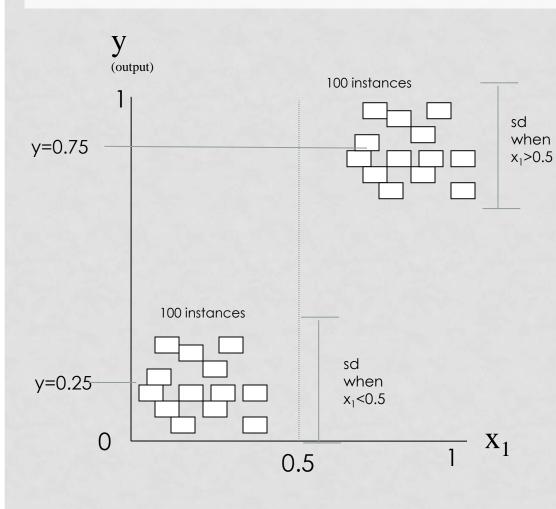
 $x_1$  or  $x_2$ ?

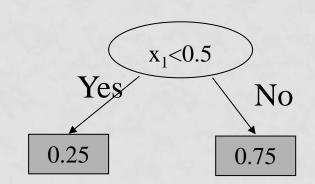
We will choose the attribute for which the average standard deviation (sd) after the partition is small:

y = 0.75100 instances 100 instances y=0.25 $\mathbf{X}_1$ 



# WHAT IS THE BEST NODE TO PUT IN THE ROOT OF THE TREE?





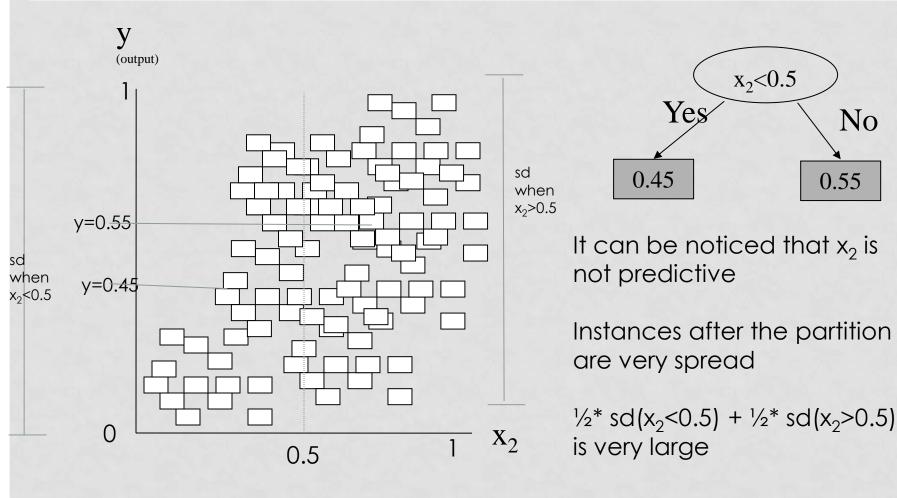
It can be noticed that  $x_1$  is quite predictive

Instances after the partition are very spread

 $\frac{1}{2}$ \*sd(x<sub>1</sub><0.5) +  $\frac{1}{2}$ \* sd(x<sub>1</sub>>0.5) is small

## WHAT IS THE BEST NODE TO PUT IN THE ROOT OF THE TREE?

No



### REFERENCES

- M5P: Model trees
- Wang, Y., & Witten, I. H. (1996). Induction of model trees for predicting continuous classes.
- http://researchcommons.waikato.ac.nz/bitstream/ handle/10289/1183/uow-cs-wp-1996-23.pdf?sequence=1